

2 Quantisation of Maxwell Field

Motivation:

- All electrodynamical processes are described by Maxwell equations. Surprisingly, the Maxwell theory is a first-quantised theory, although no Planck constant appears.

- Resolution of apparent contradiction:

spatio-temporal derivatives \leftrightarrow Compton wave length

$$\lambda_c = \frac{h}{mc} \rightarrow \frac{1}{\lambda_c} = \frac{mc}{h} \quad \text{appears in wave equation}$$

\uparrow
Heisenberg uncertainty

$\downarrow m \rightarrow 0$
 \circ

\rightarrow is gone in this limit

	S	0	$\frac{1}{2}$	1	$\frac{\infty}{2}$	∞	...
$m \neq 0$			e_{\pm}^{\pm} Dirac	W_{\pm}^{\pm}, Z^0			
$m = 0$			Weyl	Maxwell photon			

neutrinos were believed to be here

intermediary vector bosons, weak interaction

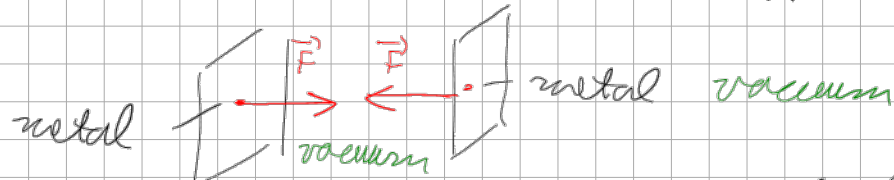
- Second quantization:

- Field-theoretical formulation for Maxwell theory: Lagrangian, Hamiltonian
- Canonical field quantization
- Problem: local gauge symmetry due to vanishing rest mass of photon
→ choose a particular gauge (Coulomb gauge)

- Three prime examples for quantum fluctuations

- Vacuum correlation function of electric field: difficult to measure, recently accomplished

• Casimir effect



- Lamb shift: degeneracy of $2\ 1/2$ and $2\ 3/2$ states in Dirac theory of hydrogen atom is lifted → fine structure in hydrogen atom

2.1 Maxwell equation:

- Forces of an electromagnetic field on charges at rest or moving are due to electric field strength \vec{E} , magnetic induction \vec{B}

- Sources for \vec{E} , \vec{B} : charge density ρ , current density \vec{j}

- Mathematical basis of Maxwell theory: Helmholtz vector decomposition theorem, once you know the divergence and the rotation of a vector field, the vector field can be determined by taking into account boundary conditions

$$\vec{V} \iff \operatorname{div} \vec{V}, \operatorname{rot} \vec{V}$$

- Electric field strength:

magnetic induction

$$\operatorname{div} \vec{E} = \frac{\rho}{\epsilon_0} \quad (1) \quad \leftarrow \text{homogeneous} \rightarrow \operatorname{div} \vec{B} = 0 \quad (2)$$

$$\operatorname{rot} \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (3) \quad \leftarrow \text{inhomogeneous} \rightarrow \operatorname{rot} \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \quad (4)$$

ϵ_0 : vacuum dielectric constant

μ_0 : vacuum permeability

light velocity

$$c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

Note: SI units (Système international d'unités)

- consistency relation: continuity equation:

$$\frac{\partial \rho}{\partial t} = \epsilon_0 \operatorname{div} \frac{\partial \vec{E}}{\partial t} \stackrel{(4)}{=} \epsilon_0 \operatorname{div} \left(c^2 \operatorname{rot} \vec{B} - \frac{1}{\epsilon_0 \mu_0} \mu_0 \vec{j} \right) = -\operatorname{div} \vec{j}$$

conservation of charges:

$$\frac{\partial}{\partial t} \underbrace{\int d^3x \rho}_{=Q} = - \underbrace{\int d^3x \operatorname{div} \vec{j}}_{\text{Gauss}} \stackrel{\text{Gauss}}{=} - \oint d\vec{S} \cdot \vec{j} \stackrel{\text{vanishes at infinity}}{=} 0$$

2.2 Local gauge symmetry:

- homogeneous Maxwell equations

$$\operatorname{div} \vec{B} = 0 \Rightarrow \vec{B} = \operatorname{rot} \vec{A} \leftarrow \text{vector potential}$$

$$\operatorname{rot} \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \operatorname{rot} \left(\vec{E} + \frac{\partial \vec{A}}{\partial t} \right) = 0 \Rightarrow \vec{E} = -\frac{\partial \vec{A}}{\partial t} - \operatorname{grad} \varphi$$

scalar potential

- inhomogeneous Maxwell equations (1) + (4):

$$\left. \begin{aligned} -\Delta \varphi - \frac{\partial}{\partial t} \operatorname{div} \vec{A} &= \frac{\rho}{\epsilon_0} \\ \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \vec{A} - \Delta \vec{A} + \operatorname{grad} \left(\frac{1}{c^2} \frac{\partial \varphi}{\partial t} + \operatorname{div} \vec{A} \right) &= \mu_0 \vec{j} \end{aligned} \right\} \text{coupled equations, solve } \varphi \text{ and } \vec{A}$$

- Invariance with respect to a local gauge invariance:

$$\begin{aligned} \varphi' &= \varphi + \frac{\partial}{\partial t} \Lambda \leftarrow \text{arbitrary gauge function} \\ \vec{A}' &= \vec{A} - \text{grad } \Lambda \end{aligned}$$

$$\vec{B}' = \text{rot } \vec{A}' = \text{rot } \vec{A} - \cancel{\text{rot grad } \Lambda} = \text{rot } \vec{A} = \vec{B}$$

$$\vec{E}' = -\text{grad } \varphi' - \frac{\partial \vec{A}'}{\partial t} = -\text{grad } \varphi - \cancel{\text{grad } \frac{\partial \Lambda}{\partial t}} - \frac{\partial \vec{A}}{\partial t} + \cancel{\frac{\partial}{\partial t} \text{grad } \Lambda} = \vec{E}$$

physics does not change but description of physics does change

- can we choose a gauge such that both coupled equations for φ and \vec{A} decouple

- Coulomb gauge: $\text{div } \vec{A} = 0$ (longitudinal part of \vec{A} vanishes)

$$\Rightarrow \Delta \varphi = -\frac{\rho}{\epsilon_0} \quad (\text{Poisson eq.}) \Rightarrow (*) \varphi(\vec{x}, t) = \int d^3x' \frac{\rho(\vec{x}', t)}{|\vec{x} - \vec{x}'|} = \text{not manifestly Lorentz invariant}$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} - \Delta \vec{A} = \mu_0 \vec{j} - \frac{1}{c^2} \frac{\partial}{\partial t} \text{grad } \varphi$$

instantaneous reaction

invariant \rightarrow only valid in certain inertial system

Only 2 degrees of freedom left

- Coulomb gauge
- φ is determined

the remaining 2 degrees of freedom correspond physical to transversal degrees of freedom

- Lorentz gauge: $\frac{1}{c^2} \frac{\partial \varphi}{\partial t} + \text{div } \vec{A} = 0$

$$\Rightarrow \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta \right) \varphi = \frac{\rho}{\epsilon_0}, \quad \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta \right) \vec{A} = \mu_0 \vec{j}$$

\Rightarrow Lorentz invariant

Disadvantage: $4 - 1 = 3$ degrees of freedom

but one should only have 2 physical degrees of freedom \Rightarrow to be explained on Monday

- From now on: vacuum $\rho(\vec{x}, t) = 0, \vec{j}(\vec{x}, t) = 0$

- Coulomb gauge: $\text{div } \vec{A} = 0$ (standard in quantum optics) (I) } radiation
(*) $\Rightarrow \psi(\vec{x}, t) \equiv 0$ (II) } gauge

$\Rightarrow \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta \right) \vec{A} = 0$ homogeneous wave equation (Strahlungsgleichung)

but also $\text{div } \vec{A} = 0$ has to be taken into account

- At the end: $\vec{E} = -\frac{\partial \vec{A}}{\partial t}, \vec{B} = \text{rot } \vec{A}$

2.3 Lagrange Formulation:

- Sim: variational principle so that Euler-Lagrange equations yield Maxwell equations

- Action: functional of vector potential $\vec{A}(\vec{x}, t)$

$$A[\vec{A}(\cdot, \cdot)] = \int dt \int d^3x \mathcal{L} \leftarrow \text{Lagrange density}$$

Lagrange function

Ansatz:

$$\mathcal{L} = \mathcal{L} \left(\underbrace{A_k(\vec{x}, t)}_{\substack{1, 2, 3 \\ \text{underline}}}, \underbrace{\frac{\partial A_k(\vec{x}, t)}{\partial t}}_{\text{underline}}, \underbrace{\partial_i A_k(\vec{x}, t)}_{\text{underline}} \right)$$

Hamilton principle:

functional derivative $\frac{\delta A}{\delta A_k(\vec{x}, t)} = 0$

- Crash course on functional derivatives:

$$\frac{dx}{dx} = 1, \quad \frac{\partial x_i}{\partial x_j} = \delta_{ij}, \quad \frac{\delta x(t)}{\delta x(t')} = \delta(t-t')$$

total derivative, partial derivative, functional derivative

$$\Rightarrow \frac{\delta A_e(\vec{x}, t)}{\delta A_e(\vec{x}', t')} = \delta_{ee} \delta(\vec{x} - \vec{x}') \delta(t-t')$$

- Greiner, Reinhardt: Field Quantization
- My QFT lecture notes

Einstein summation convention

$$\begin{aligned} \frac{\delta A}{\delta A_e(\vec{x}, t)} &= \int dt' \int d^3x' \left\{ \frac{\partial \mathcal{L}}{\partial A_e(\vec{x}', t')} \frac{\delta A_e(\vec{x}', t')}{\delta A_e(\vec{x}, t)} + \frac{\partial \mathcal{L}}{\partial \frac{\partial A_e(\vec{x}', t')}{\partial t'}} \frac{\delta \frac{\partial A_e(\vec{x}', t')}{\partial t'}}{\delta A_e(\vec{x}, t)} \right. \\ &\quad \left. + \frac{\partial \mathcal{L}}{\partial [\partial'_i A_e(\vec{x}', t')]} \frac{\delta \partial'_i A_e(\vec{x}', t')}{\delta A_e(\vec{x}, t)} \right\} \\ &= \partial'_i \frac{\delta A_e(\vec{x}', t')}{\delta A_e(\vec{x}, t)} \end{aligned}$$

$$\begin{aligned} &\frac{\delta \frac{\partial A_e(\vec{x}', t')}{\partial t'}}{\delta A_e(\vec{x}, t)} \\ &= \frac{\partial}{\partial t'} \frac{\delta A_e(\vec{x}', t')}{\delta A_e(\vec{x}, t)} \end{aligned}$$

partial integration

$$= \int dt' \int d^3x' \left\{ \frac{\partial \mathcal{L}}{\partial A_e(\vec{x}', t')} - \frac{\partial}{\partial t'} \frac{\partial \mathcal{L}}{\partial \frac{\partial A_e(\vec{x}', t')}{\partial t'}} - \partial'_i \frac{\partial \mathcal{L}}{\partial \partial'_i A_e(\vec{x}', t')} \right\} \frac{\delta A_e(\vec{x}', t')}{\delta A_e(\vec{x}, t)} = 0$$

Euler-Lagrange equations:

$$\frac{\partial \mathcal{L}}{\partial A_e(\vec{x}, t)} - \frac{\partial}{\partial t} \frac{\partial \mathcal{L}}{\partial \frac{\partial A_e(\vec{x}, t)}{\partial t}} - \partial_i \frac{\partial \mathcal{L}}{\partial \partial_i A_e(\vec{x}, t)} = 0$$

$$= \delta_{ee} \delta(\vec{x} - \vec{x}') \delta(t-t')$$