

Last Time:

Field operator: $\hat{\vec{A}}(\vec{x}, t)$

• Homogeneous wave equation:

• Coulomb gauge:

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta \right) \vec{A}(\vec{x}, t) = \vec{0} \quad (*)$$

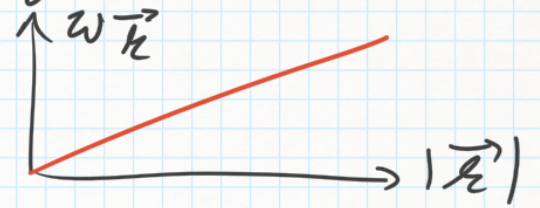
$$\text{div } \vec{A}(\vec{x}, t) = 0$$

2.8 Solution of Wave Equation:

$$\hat{\vec{A}}(\vec{x}, t) = \int d^3k \hat{\vec{A}}(\vec{k}, t) e^{i\vec{k}\vec{x}} \quad \rightarrow \text{inserting in (1)}$$

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} + \underbrace{\vec{k}^2}_{= \omega_{\vec{k}}^2} c^2 \right) \hat{\vec{A}}(\vec{k}, t) = \vec{0}$$

linear dispersion



harmonic oscillator equation:

$$\hat{A}(\vec{k}, t) = \hat{A}^{(1)}(\vec{k}) e^{-i\omega_{\vec{k}} t} + \hat{A}^{(2)}(\vec{k}) e^{+i\omega_{\vec{k}} t}$$

$$\hat{\vec{A}}(\vec{x}, t) = \int d^3k \left\{ \hat{\vec{A}}^{(1)}(\vec{k}) e^{i(\vec{k}\vec{x} - \omega_{\vec{k}}t)} + \hat{\vec{A}}^{(2)}(\vec{k}) e^{i(\vec{k}\vec{x} + \omega_{\vec{k}}t)} \right\}$$

$$\vec{k} \rightarrow -\vec{k} \quad \hat{\vec{A}}^{(2)}(-\vec{k}) e^{-i(\vec{k}\vec{x} - \omega_{\vec{k}}t)}$$

$$\omega_{-\vec{k}} = \omega_{\vec{k}}$$

real vector potential: $\vec{A}(\vec{x}, t) = \vec{A}'(\vec{x}, t)$

field operator has to be self-adjoint: $\hat{\vec{A}}(\vec{x}, t) = \hat{\vec{A}}^\dagger(\vec{x}, t)$

$$\hat{\vec{A}}^\dagger(\vec{x}, t) = \int d^3k \left\{ \hat{\vec{A}}^{(1)\dagger}(\vec{k}) e^{-i(\vec{k}\vec{x} - \omega_{\vec{k}}t)} + \hat{\vec{A}}^{(2)\dagger}(\vec{k}) e^{+i(\vec{k}\vec{x} - \omega_{\vec{k}}t)} \right\}$$

$$\Rightarrow \hat{\vec{A}}^{(1)\dagger}(\vec{k}) = \hat{\vec{A}}^{(2)\dagger}(-\vec{k}) \Leftrightarrow \hat{\vec{A}}^{(1)\dagger}(\vec{k}) = \hat{\vec{A}}^{(2)}(-\vec{k})$$

One degree of freedom is eliminated:

$$\hat{\vec{A}}(\vec{k}) := \hat{\vec{A}}^{(1)}(\vec{k}), \quad \hat{\vec{A}}^{(2)}(\vec{k}) = \hat{\vec{A}}^\dagger(-\vec{k})$$

$$\hat{\vec{A}}(\vec{x}, t) = \int d^3k \left\{ \hat{\vec{A}}(\vec{k}) e^{i(\vec{k}\vec{x} - \omega_{\vec{k}}t)} + \hat{\vec{A}}^\dagger(\vec{k}) e^{-i(\vec{k}\vec{x} - \omega_{\vec{k}}t)} \right\}$$

2.8 Polarization Vectors:

step back: more detailed understanding of plane waves

consider two plane waves with \vec{k} , $\omega_{\vec{k}} = c|\vec{k}|$:

$$\vec{A}_1(\vec{x}, t) = A_1 \vec{E}_1 e^{i(\vec{k} \cdot \vec{x} - \omega_{\vec{k}} t)} \quad \vec{A}_2(\vec{x}, t) = A_2 \vec{E}_2 e^{i(\vec{k} \cdot \vec{x} - \omega_{\vec{k}} t)}$$

A_i : complex amplitudes, \vec{E}_i : polarization vectors
linear polarized plane waves \rightarrow *unique polarization*

orthonormal: $\vec{E}_i^* \cdot \vec{E}_j = \delta_{ij}$

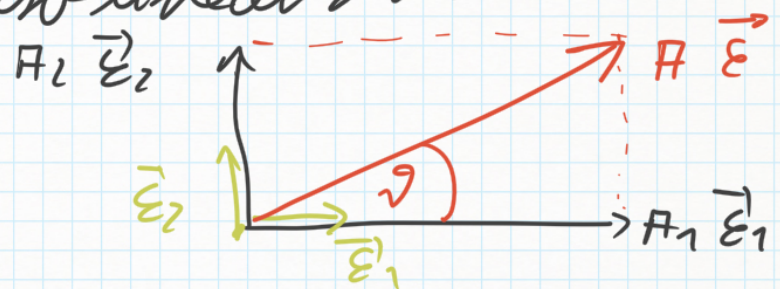
$$\vec{A}(\vec{x}, t) = \vec{A}_1(\vec{x}, t) + \vec{A}_2(\vec{x}, t) = (A_1 \vec{E}_1 + A_2 \vec{E}_2) e^{i(\vec{k} \cdot \vec{x} - \omega_{\vec{k}} t)}$$

general case: $A_1 = |A_1| e^{i\varphi_1}$, $A_2 = |A_2| e^{i\varphi_2}$

special case: $\varphi_1 = \varphi_2 = \varphi \Rightarrow$ sum is also linear polarization

$$\Rightarrow \vec{A}(\vec{x}, t) = A \vec{E} e^{i(\vec{k} \cdot \vec{x} - \omega_{\vec{k}} t)}$$

$$A = \sqrt{|A_1|^2 + |A_2|^2}, \quad \vartheta = \arctan \frac{|A_2|}{|A_1|}$$



$\rho_1 \neq \rho_2$; elliptically polarized plane wave

Illustration: circularly polarized " "

$$A_1 = \frac{A_0}{\sqrt{2}}, \quad A_2 = \pm i \frac{A_0}{\sqrt{2}}; \quad \rho_2 - \rho_1 = \pm \frac{\pi}{2}$$

$$\Rightarrow \vec{A}(\vec{x}, t) = \frac{A_0}{\sqrt{2}} \left(\vec{e}_1 \pm i \vec{e}_2 \right) e^{i(\vec{k} \cdot \vec{x} - \omega \vec{e}_z t)}$$

concrete:

$$\vec{k} = \begin{pmatrix} 0 \\ 0 \\ k \end{pmatrix},$$

$$\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix},$$

$$\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

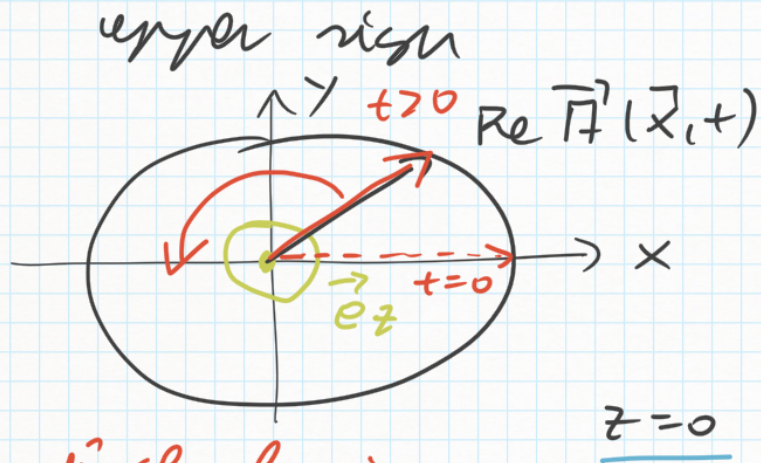
propagation
in z -direction

polarization in $x-y$ -plane

$$\vec{A}(\vec{x}, t) = \frac{A_0}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \\ 0 \end{pmatrix} e^{i(\underbrace{k \vec{e}_z \cdot \vec{x} - \omega \vec{e}_z t}_{= k(z - ct)})}$$

\rightarrow real part is physical

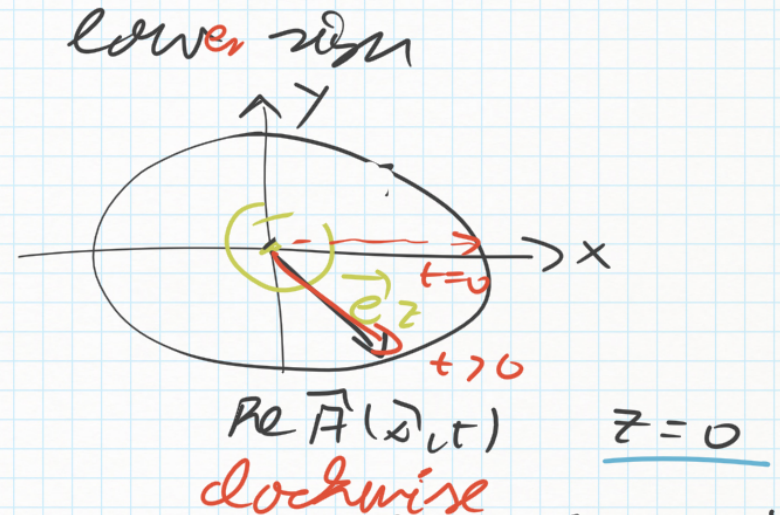
$$\text{Re } \vec{A}(\vec{r}, t) = \frac{A_0}{\sqrt{2}} \begin{pmatrix} \cos k(z - ct) \\ + \sin k(z - ct) \\ 0 \end{pmatrix}$$



anti-clockwise

observed for somebody looking in the direction of the incoming laser beam

optics: left-circular polarized
elementary particle physics positive helicity



clockwise

right-circular polarized
negative helicity

2.9 Construct of Polarization Vectors:

Aim: define helicity of an electromagnetic wave

Motivation: characterization properties of a photon

spin $1 \hat{=} \text{intrinsic angular momentum}$

rest mass = 0



Method: representation theory of rotations

most general rotation matrices:



$$R_{jk}(\vec{\varphi}) = \frac{\varphi_i}{|\vec{\varphi}|} \epsilon_{ijk} \sin|\vec{\varphi}| + \frac{\varphi_j \varphi_k}{|\vec{\varphi}|^2} (1 - \cos|\vec{\varphi}|) + \delta_{jk} \cos|\vec{\varphi}|$$

• Rotation axis $\vec{\varphi}$: $R_{jk}(\vec{\varphi}) \varphi_k = \underline{(+1)} \cdot \varphi_j \checkmark$

• Rotation angle $|\vec{\varphi}|$:

$$\text{Tr } R(\vec{\varphi}) = R_{jj}(\vec{\varphi}) = 1 - \cos|\vec{\varphi}| + 3 \cdot \cos|\vec{\varphi}| = 1 + 2 \cos|\vec{\varphi}| \checkmark$$

↓ infinitesimal rotation

generators of rotations = spin \vec{S}

$$(S_m)_{jk} = i \left. \frac{\partial R_{jk}(\vec{\varphi})}{\partial \varphi_m} \right|_{\vec{\varphi}=\vec{0}}$$

$$S_1 = i \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}, \quad S_2 = -i \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \quad S_3 = i \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

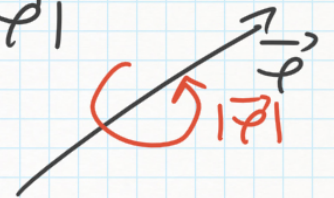
$$\Rightarrow [S_i, S_j]_- = i \epsilon_{ijk} S_k$$

angular momentum algebra

Lie theorem ↑

$$R(\vec{\varphi}) = e^{-i \vec{\varphi} \cdot \vec{S}}$$

3x3 matrix
3x3 matrix



definition helicity:

$$\hat{h}(\vec{k}) = \frac{\vec{k}}{|\vec{k}|} \cdot \vec{S} = k_x S_x + k_y S_y + k_z S_z = \frac{i}{k} \begin{pmatrix} 0 & -k_z & k_y \\ k_z & 0 & -k_x \\ -k_y & k_x & 0 \end{pmatrix}$$

polarisation vector $\vec{\epsilon}(\vec{k}, \lambda)$

helicity $\lambda = \pm 1$

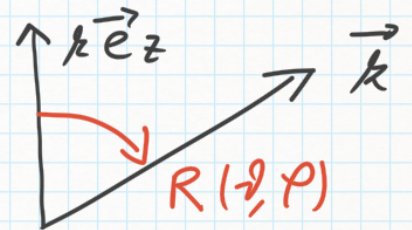
$$\vec{A}(\vec{x}, t) = A \vec{\epsilon}(\vec{k}, \lambda) e^{i(\vec{k} \cdot \vec{x} - \omega \vec{a} t)}$$

$$\Rightarrow \hat{h}(\vec{k}) \vec{\epsilon}(\vec{k}, \lambda) = \lambda \vec{\epsilon}(\vec{k}, \lambda)$$

example: $\vec{\epsilon}(k \vec{e}_z, \lambda) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \lambda i \\ 0 \end{pmatrix}$; $\hat{h}(k \vec{e}_z) = S_3 = i \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$\hat{h}(k \vec{e}_z) \vec{\epsilon}(k \vec{e}_z, \lambda) = i \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ \lambda i \\ 0 \end{pmatrix} \frac{1}{\sqrt{2}} = \lambda \vec{\epsilon}(k \vec{e}_z, \lambda)$$

$$\vec{k} = k \begin{pmatrix} \sin \vartheta \cos \varphi \\ \sin \vartheta \sin \varphi \\ \cos \vartheta \end{pmatrix} = \underbrace{R(\vartheta, \varphi)}_{= R_z(\varphi) R_y(\vartheta)} k \vec{e}_z$$



$$R_z(\varphi) = e^{-iS_z \varphi} = \begin{pmatrix} \cos \varphi & \sin \varphi & 0 \\ -\sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$R_y(\vartheta) = e^{-iS_y \vartheta} = \begin{pmatrix} \cos \vartheta & 0 & \sin \vartheta \\ 0 & 1 & 0 \\ -\sin \vartheta & 0 & \cos \vartheta \end{pmatrix}$$

$$R(\vartheta, \varphi) = R_z(\varphi) R_y(\vartheta) = \begin{pmatrix} \cos \vartheta \cos \varphi & -\sin \varphi & \sin \vartheta \cos \varphi \\ \cos \vartheta \sin \varphi & \cos \varphi & \sin \vartheta \sin \varphi \\ -\sin \vartheta & 0 & \cos \vartheta \end{pmatrix}$$

$$\vec{k} = R(\vartheta, \varphi) \hat{k} \quad \vec{e}_z \hat{=} \vec{e}'(\vec{k}, \lambda) = R(\vartheta, \varphi) \vec{e}(\hat{k} \vec{e}_z, \lambda)$$

$$\Rightarrow \vec{e}'(\vec{k}, \lambda) \stackrel{\text{exercice}}{=} \frac{1}{\sqrt{2}} \begin{pmatrix} \cos \vartheta \cos \varphi - \lambda i \sin \varphi \\ \cos \vartheta \sin \varphi + \lambda i \cos \varphi \\ -\sin \vartheta \end{pmatrix}$$

$$\hat{h}(\vec{k}) \vec{e}'(\vec{k}, \lambda) \stackrel{\text{exercice}}{=} \lambda \vec{e}'(\vec{k}, \lambda) \quad \checkmark$$

$$\vec{e}'(\vec{k}, \lambda) \Big|_{\vec{k} = \hat{k} \vec{e}_z} \stackrel{\vartheta=0, \varphi=0}{=} \vec{e}(\hat{k} \vec{e}_z, \lambda) \quad \checkmark$$