

4. Canonical Field Quantisation for Bosons:

Motivation:

1 classical particle $\xrightarrow{\text{"first quantisation"}}$ 1 quantum particle
 1 quantum particle $\xrightarrow{\text{"second quantisation"}}$ arbitrary number of quantum particles
systematically derived via canonical field quantisation

4.1 Action of Schrödinger Field:

Task: Schrödinger equation of motion \longleftrightarrow action

$$i\hbar \frac{\partial \psi(\vec{x}, t)}{\partial t} = \left\{ -\frac{\hbar^2}{2m} \Delta + V_1(\vec{x}) \right\} \psi(\vec{x}, t) \quad | \cdot \delta \psi^*(\vec{x}, t)$$

$$-i\hbar \frac{\partial \psi^*(\vec{x}, t)}{\partial t} = \left\{ -\frac{\hbar^2}{2m} \Delta + V_1(\vec{x}) \right\} \psi^*(\vec{x}, t) \quad | -\delta \psi(\vec{x}, t)$$

$$\int dt \int d^3x \left\{ i\hbar \left[\delta \psi^*(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t} - \psi(\vec{x}, t) \frac{\partial \delta \psi^*(\vec{x}, t)}{\partial t} \right] - V_1(\vec{x}) \left[\delta \psi^*(\vec{x}, t) \psi(\vec{x}, t) + \psi(\vec{x}, t) \delta \psi^*(\vec{x}, t) \right] \right\} = 0$$

$$= \delta \left[\int dt \int d^3x \left(\psi^*(\vec{x}, t) \psi(\vec{x}, t) \right) \right]$$

1. partial integration: assume that variations of Schrödinger fields ψ, ψ^* vanish at integration boundary

$$\int dt \textcircled{1} = \int dt \left\{ \delta \psi^*(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t} + \left(\frac{\partial}{\partial t} \delta \psi(\vec{x}, t) \right) \cdot \psi^*(\vec{x}, t) \right\} = \delta \int dt \psi^*(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t}$$

$$= \delta \int dt \psi(\vec{x}, t)$$

2. partial integration:

$$\int d^3x \textcircled{2} = - \int d^3x \left\{ \vec{\nabla} \delta \psi^*(\vec{x}, t) \cdot \vec{\nabla} \psi(\vec{x}, t) + \vec{\nabla} \delta \psi(\vec{x}, t) \cdot \vec{\nabla} \psi^*(\vec{x}, t) \right\} = - \delta \int d^3x \vec{\nabla} \psi^*(\vec{x}, t) \cdot \vec{\nabla} \psi(\vec{x}, t)$$

$$= \delta \int d^3x \psi^*(\vec{x}, t) \Delta \psi(\vec{x}, t)$$

$\Rightarrow \delta \Delta[\psi^*(\cdot, \cdot); \psi(\cdot, \cdot)] = 0$ Hamilton minimum of classical field theory

$$\mathcal{A} = \int dt L \left[\psi^*(\cdot, t), \frac{\partial \psi^*(\cdot, t)}{\partial t}; \psi(\cdot, t), \frac{\partial \psi(\cdot, t)}{\partial t} \right] \quad \text{action}$$

$$L = \int d^3x \mathcal{L} \left(\psi^*(\vec{x}, t), \vec{\nabla} \psi^*(\vec{x}, t), \frac{\partial \psi^*(\vec{x}, t)}{\partial t}; \psi(\vec{x}, t), \vec{\nabla} \psi(\vec{x}, t), \frac{\partial \psi(\vec{x}, t)}{\partial t} \right) \quad \text{Lagrange function}$$

$$\mathcal{L} = i\hbar \psi^*(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t} - \frac{\hbar^2}{2m} \vec{\nabla} \psi^*(\vec{x}, t) \cdot \vec{\nabla} \psi(\vec{x}, t) - V_1(\vec{x}) \psi^*(\vec{x}, t) \psi(\vec{x}, t) \quad \text{Lagrange density}$$

4.2 Functional Derivative: Definition

Overview:

$$\frac{d\mathcal{F}(q)}{dq} \quad \text{total derivative for one variable}$$

$$\frac{d\mathcal{F}}{dq} = 1$$

$$\frac{\partial \mathcal{F}(q_1, \dots, q_N)}{\partial q_i} \quad \text{partial derivative for finite number of variables}$$

$$\frac{\partial \mathcal{F}}{\partial q_i} = \delta_{ij}$$

$$\delta \mathcal{F}(q_1, \dots, q_N) = \sum_{i=1}^N \frac{\partial \mathcal{F}(q_1, \dots, q_N)}{\partial q_i} \cdot dq_i$$

functional: mapping of a function to $\mathbb{R}(\mathbb{C})$

$$\frac{\delta F[\phi(\cdot)]}{\delta \phi(x)}$$

functional derivative for a continuum of variables

$$\frac{\delta \phi(x)}{\delta \phi(y)} = \delta(x-y)$$

special case: $\delta q_i = \epsilon \delta_{ij}$

$$\mathcal{F}(q_1, \dots, q_i + \epsilon, \dots, q_N) - \mathcal{F}(q_1, \dots, q_i, \dots, q_N) = d\mathcal{F}(q_1, \dots, q_N) = \sum_{i=1}^N \frac{\partial \mathcal{F}(q_1, \dots, q_N)}{\partial q_i} \epsilon \delta_{ij} = \epsilon \cdot \frac{\partial \mathcal{F}(q_1, \dots, q_N)}{\partial q_i}$$

$$\Rightarrow \frac{\partial \mathcal{F}(q_1, \dots, q_N)}{\partial q_i} = \lim_{\epsilon \rightarrow 0} \frac{\mathcal{F}(q_1, \dots, q_i + \epsilon, \dots, q_N) - \mathcal{F}(q_1, \dots, q_N)}{\epsilon}$$

Functional derivatives:

$$\delta F[\phi(\cdot)] = \int dx \frac{\delta F[\phi(\cdot)]}{\delta \phi(x)} \delta \phi(x)$$

special case: $\delta \phi(x) = \epsilon \delta(x-y)$

$$F[\phi(\cdot) + \epsilon \delta(\cdot-y)] - F[\phi(\cdot)] = \delta F[\phi(\cdot)] = \int dx \frac{\delta F[\phi(\cdot)]}{\delta \phi(x)} \epsilon \delta(x-y) = \epsilon \frac{\delta F[\phi(\cdot)]}{\delta \phi(y)}$$

$$\Rightarrow \frac{\delta F[\phi(\cdot)]}{\delta \phi(y)} = \lim_{\epsilon \rightarrow 0} \frac{F[\phi(\cdot) + \epsilon \delta(\cdot-y)] - F[\phi(\cdot)]}{\epsilon}$$

\Rightarrow definition as limit of difference quotient
 \Rightarrow starting point to derive calculational rules

Consequences:

1) "Formal" functional derivative:

$$\frac{\delta f(x)}{\delta f(y)} = \lim_{\epsilon \rightarrow 0} \frac{f(x) + \epsilon \delta(x-y) - f(x)}{\epsilon} = \delta(x-y)$$

2) Product rule:

$$\frac{\delta \{F[\phi(\cdot)] \cdot G[\phi(\cdot)]\}}{\delta \phi(y)} = \lim_{\epsilon \downarrow 0} \frac{1}{\epsilon} \left\{ F[\phi(\cdot) + \epsilon \delta(\cdot - y)] G[\phi(\cdot) + \epsilon \delta(\cdot - y)] - F[\phi(\cdot)] G[\phi(\cdot) + \epsilon \delta(\cdot - y)] + F[\phi(\cdot)] G[\phi(\cdot) + \epsilon \delta(\cdot - y)] - F[\phi(\cdot)] G[\phi(\cdot)] \right\}$$

$$= \frac{\delta F[\phi(\cdot)]}{\delta \phi(y)} G[\phi(\cdot)] + F[\phi(\cdot)] \cdot \frac{\delta G[\phi(\cdot)]}{\delta \phi(y)}$$

3) Chain rule:

$$\frac{\delta f(\phi(x))}{\delta \phi(y)} = \frac{\partial f(\phi(x))}{\partial \phi(x)} \cdot \frac{\delta \phi(x)}{\delta \phi(y)} = \frac{\partial f(\phi(x))}{\partial \phi(x)} \delta(x-y)$$

4.3 Functional derivatives: Application:

$$[\hat{a}_{\vec{x}_n}, \dots, \hat{a}_{\vec{x}_1}, \hat{a}_{\vec{x}}^+]_- = \sum_{z=1}^n \delta(\vec{x} - \vec{x}_z) \hat{a}_{\vec{x}_n} \dots \hat{a}_{\vec{x}_{z+1}} \hat{a}_{\vec{x}_{z-1}} \dots \hat{a}_{\vec{x}_1}$$

$$= \frac{\delta}{\delta \hat{a}_{\vec{x}}} \hat{a}_{\vec{x}_n} \dots \hat{a}_{\vec{x}_1}$$

generalised to arbitrary functional:

$$F[\hat{a}_{\cdot}] = \int d^3x_1 \dots \int d^3x_n F_n(\vec{x}_1, \dots, \vec{x}_n) \hat{a}_{\vec{x}_n} \dots \hat{a}_{\vec{x}_1}$$

$$[F[\hat{a}_{\cdot}], \hat{a}_{\vec{x}}^+]_- = \frac{\delta}{\delta \hat{a}_{\vec{x}}} F[\hat{a}_{\cdot}] \quad (1)$$

analogously: $[\hat{a}_{\vec{x}}, F[\hat{a}_{\cdot}^+]]_- = \frac{\delta}{\delta \hat{a}_{\vec{x}}^+} F[\hat{a}_{\cdot}^+] \quad (2)$

application: $[\hat{a}_{\vec{x}}, \hat{a}_{\vec{x}'}^+]_- \stackrel{(1)}{=} \frac{\delta}{\delta \hat{a}_{\vec{x}'}} \hat{a}_{\vec{x}} \stackrel{(2)}{=} \frac{\delta}{\delta \hat{a}_{\vec{x}'}} \hat{a}_{\vec{x}}^+ = \delta(\vec{x} - \vec{x}')$

further generalisation to functional $F[\hat{a}_{\cdot}^+, \hat{a}_{\cdot}]$ with normal ordering

$$[F[\hat{a}_{\cdot}^+, \hat{a}_{\cdot}], \hat{a}_{\vec{x}}^+]_- = F[\hat{a}_{\cdot}^+, \hat{a}_{\cdot}] \frac{\delta}{\delta \hat{a}_{\vec{x}}}$$

$$[\hat{a}_{\vec{x}}, F[\hat{a}_{\cdot}^+, \hat{a}_{\cdot}]]_- = \frac{\delta}{\delta \hat{a}_{\vec{x}}^+} F[\hat{a}_{\cdot}^+, \hat{a}_{\cdot}]$$

application: $[\hat{a}_{\vec{x}}^+, \hat{a}_{\vec{x}'}^+]_- = \hat{a}_{\vec{x}}^+ \frac{\delta}{\delta \hat{a}_{\vec{x}'}} = 0, [\hat{a}_{\vec{x}}, \hat{a}_{\vec{x}'}]_- = \frac{\delta}{\delta \hat{a}_{\vec{x}'}} \hat{a}_{\vec{x}} = 0$

extension from Schrödinger to Heisenberg picture

$$[F[\hat{\psi}^+(\cdot, \cdot), \hat{\psi}(\cdot, \cdot)], \hat{\psi}^+(\vec{x}, t)]_- = F[\hat{\psi}^+(\cdot, \cdot), \hat{\psi}(\cdot, \cdot)] \frac{\delta}{\delta \hat{\psi}^+(\vec{x}, t)}$$

$$[\hat{\psi}(\vec{x}, t), F[\hat{\psi}^+(\cdot, \cdot), \hat{\psi}(\cdot, \cdot)]]_- = \frac{\delta}{\delta \hat{\psi}^+(\vec{x}, t)} F[\hat{\psi}^+(\cdot, \cdot), \hat{\psi}(\cdot, \cdot)]$$

Heisenberg equations:

$$i\hbar \frac{\partial}{\partial t} \hat{\psi}(\vec{x}, t) = [\hat{\psi}(\vec{x}, t), \hat{H}_H(t)]_- = \frac{\delta}{\delta \hat{\psi}^+(\vec{x}, t)} \hat{H}_H(t)$$

$$i\hbar \frac{\partial}{\partial t} \hat{\psi}^+(\vec{x}, t) = [\hat{\psi}^+(\vec{x}, t), \hat{H}_H(t)]_- = -\hat{H}_H(t) \frac{\delta}{\delta \hat{\psi}(\vec{x}, t)}$$

ABC-rules \Leftrightarrow functional derivatives (normal ordered)

4.4 Euler-Lagrange Equations:

$$\delta \mathcal{A} = \int d^4x \left\{ \frac{\delta \mathcal{A}}{\delta \psi^*(\vec{x}, t)} \delta \psi^*(\vec{x}, t) + \frac{\delta \mathcal{A}}{\delta \psi(\vec{x}, t)} \delta \psi(\vec{x}, t) \right\} \stackrel{!}{=} 0 \Rightarrow \begin{cases} \frac{\delta \mathcal{A}}{\delta \psi^*(\vec{x}, t)} = 0 \\ \frac{\delta \mathcal{A}}{\delta \psi(\vec{x}, t)} = 0 \end{cases}$$

$$\mathcal{A} = \int dt^1 L[\psi^*(\cdot, t^1), \frac{\partial \psi^*(\cdot, t^1)}{\partial t^1}; \psi(\cdot, t^1), \frac{\partial \psi(\cdot, t^1)}{\partial t^1}]$$

$$\frac{\delta \mathcal{A}}{\delta \psi^*(\vec{x}, t)} = \int d^3x \left\{ \frac{\delta L}{\delta \psi^*(\vec{x}, t)} + \frac{\delta \psi^*(\vec{x}, t)}{\delta \psi^*(\vec{x}, t)} \frac{\delta L}{\delta \psi^*(\vec{x}, t)} + \frac{\delta L}{\delta \frac{\partial \psi^*(\vec{x}, t)}{\partial t^1}} \frac{\delta \frac{\partial \psi^*(\vec{x}, t)}{\partial t^1}}{\delta \psi^*(\vec{x}, t)} \right\}$$

$$= \frac{\partial}{\partial t^1} \frac{\delta \psi^*(\vec{x}, t^1)}{\delta \psi^*(\vec{x}, t)}$$

partial integration:

$$\frac{\partial}{\partial t^1} \frac{\delta \psi^*(\vec{x}, t^1)}{\delta \psi^*(\vec{x}, t)}$$

$$= \int d^3x \left\{ \frac{\delta L}{\delta \psi^*(\vec{x}, t)} - \frac{\partial}{\partial t} \frac{\delta L}{\delta \dot{\psi}^*(\vec{x}, t)} \right\} \frac{\delta \psi^*(\vec{x}, t)}{\delta \psi^*(\vec{x}, t)} = \frac{\delta L}{\delta \psi^*(\vec{x}, t)} - \frac{\partial}{\partial t} \frac{\delta L}{\delta \dot{\psi}^*(\vec{x}, t)} \stackrel{!}{=} 0 \quad (1)$$

$$L = \int d^3x \mathcal{L}(\psi^*(\vec{x}, t), \vec{\nabla} \psi^*(\vec{x}, t), \frac{\partial \psi^*(\vec{x}, t)}{\partial t}; \psi(\vec{x}, t), \vec{\nabla} \psi(\vec{x}, t), \frac{\partial \psi(\vec{x}, t)}{\partial t})$$

$$\frac{\delta L}{\delta \psi^*(\vec{x}, t)} = \frac{\partial \mathcal{L}}{\partial \psi^*(\vec{x}, t)} - \vec{\nabla} \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \psi^*(\vec{x}, t)} \quad (2)$$

(1) + (2): Euler-Lagrange equation of field theory

$$\frac{\partial \mathcal{L}}{\partial \psi^*(\vec{x}, t)} - \vec{\nabla} \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \psi^*(\vec{x}, t)} - \frac{\partial}{\partial t} \frac{\partial \mathcal{L}}{\partial \dot{\psi}^*(\vec{x}, t)} = 0 \quad (3)$$

$$\frac{\partial \mathcal{L}}{\partial \psi(\vec{x}, t)} - \vec{\nabla} \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \psi(\vec{x}, t)} - \frac{\partial}{\partial t} \frac{\partial \mathcal{L}}{\partial \dot{\psi}(\vec{x}, t)} = 0 \quad (4)$$

$$\mathcal{L} = i\hbar \psi^* \frac{\partial \psi}{\partial t} - \frac{\hbar^2}{2m} \nabla \psi^* \nabla \psi - V_1 \psi^* \psi \quad (5)$$

$$\frac{\partial \mathcal{L}}{\partial \psi^*} = i\hbar \frac{\partial \psi}{\partial t} - V_1 \psi, \quad \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \psi^*} = -\frac{\hbar^2}{2m} \vec{\nabla} \psi, \quad \frac{\partial \mathcal{L}}{\partial \dot{\psi}^*} = 0$$

$$\frac{\partial \mathcal{L}}{\partial \psi} = -V_1 \psi, \quad \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \psi} = -\frac{\hbar^2}{2m} \vec{\nabla} \psi, \quad \frac{\partial \mathcal{L}}{\partial \dot{\psi}} = i\hbar \psi^* \quad (6)$$

$$(5) \text{ in } (3): i\hbar \frac{\partial \psi}{\partial t} - V_1 \psi - \frac{\hbar^2}{2m} \Delta \psi = 0 \Rightarrow i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \Delta \psi + V_1 \psi \quad \checkmark$$

$$(6) \text{ in } (4): -V_1 \psi^* - \frac{\hbar^2}{2m} \Delta \psi^* - i\hbar \frac{\partial \psi^*}{\partial t} = 0 \Rightarrow -i\hbar \frac{\partial \psi^*}{\partial t} = -\frac{\hbar^2}{2m} \Delta \psi^* + V_1 \psi^* \quad \checkmark$$

4.5 Hamilton Field Theory: canonical momentum fields

$$\pi^*(\vec{x}, t) = \frac{\delta L}{\delta \dot{\psi}^*(\vec{x}, t)} = \frac{\partial \mathcal{L}}{\partial \dot{\psi}^*(\vec{x}, t)} = 0$$

$$\pi(\vec{x}, t) = \frac{\delta L}{\delta \dot{\psi}(\vec{x}, t)} = \frac{\partial \mathcal{L}}{\partial \dot{\psi}(\vec{x}, t)} = i\hbar \psi^*(\vec{x}, t)$$

Hamilton function via Legendre transformation:

$$H = \int d^3x \left\{ \pi^*(\vec{x}, t) \frac{\partial \psi^*(\vec{x}, t)}{\partial t} + \pi(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t} - L \right\}$$

$$H = \int d^3x \mathcal{H}(\pi^*(\vec{x}, t), \vec{\nabla} \pi^*(\vec{x}, t); \psi(\vec{x}, t), \vec{\nabla} \psi(\vec{x}, t))$$

Hamilton density

$$\mathcal{H} = \frac{\hbar}{2mi} \vec{\nabla} \pi \cdot \vec{\nabla} \psi + V_1 \pi \cdot \psi$$

Hamilton equations of field theory? $\Delta = \Delta[\pi(\cdot, \cdot); \psi(\cdot, \cdot)]$

$$\delta \Delta = \int dt \int d^3x \left\{ \frac{\delta \Delta}{\delta \pi(\vec{x}, t)} \delta \pi(\vec{x}, t) + \frac{\delta \Delta}{\delta \psi(\vec{x}, t)} \delta \psi(\vec{x}, t) \right\} = 0 \quad \text{Hamilton principle}$$

$$\Delta = \int dt L = \int dt \int d^3x \pi(\vec{x}, t) \frac{\partial \psi(\vec{x}, t)}{\partial t} - \int dt H[\pi(\cdot, t); \psi(\cdot, t)]$$

$$\frac{\delta \Delta}{\delta \pi(\vec{x}, t)} = \frac{\partial \psi(\vec{x}, t)}{\partial t} - \frac{\delta H}{\delta \pi(\vec{x}, t)} \quad [\text{analogue: } \dot{q} = \frac{\partial H}{\partial p}]$$

$$\frac{\delta \Delta}{\delta \psi(\vec{x}, t)} = -\frac{\partial \pi(\vec{x}, t)}{\partial t} - \frac{\delta H}{\delta \psi(\vec{x}, t)} \quad [\text{analogue: } \dot{p} = -\frac{\partial H}{\partial q}]$$

$$\frac{\delta H}{\delta \pi(\vec{x}, t)} = \frac{\partial \psi}{\partial t} - \vec{\nabla} \frac{\partial \mathcal{H}}{\partial \vec{\nabla} \pi(\vec{x}, t)}$$

$$\frac{\delta H}{\delta \psi(\vec{x}, t)} = \frac{\partial \mathcal{H}}{\partial \psi(\vec{x}, t)} - \vec{\nabla} \frac{\partial \mathcal{H}}{\partial \vec{\nabla} \psi(\vec{x}, t)}$$

$$\frac{\partial \mathcal{H}}{\partial \pi} = \frac{V_1}{i\hbar} \psi, \quad \frac{\partial \mathcal{H}}{\partial \vec{\nabla} \pi} = \frac{\hbar}{2mi} \vec{\nabla} \psi \Rightarrow \frac{\partial \psi}{\partial t} = \frac{\delta H}{\delta \pi} = \frac{V_1}{i\hbar} \psi - \frac{\hbar}{2mi} \Delta \psi$$

$$\frac{\partial \mathcal{H}}{\partial \psi} = \frac{V_1}{i\hbar} \pi, \quad \frac{\partial \mathcal{H}}{\partial \vec{\nabla} \psi} = \frac{\hbar}{2mi} \vec{\nabla} \pi \Rightarrow -\frac{\partial \pi}{\partial t} = \frac{V_1}{i\hbar} \pi - \frac{\hbar}{2mi} \Delta \pi$$

$$\pi = i\hbar \psi^* \Rightarrow -i\hbar \frac{\partial \psi^*}{\partial t} = -\frac{\hbar^2}{2m} \Delta \psi^* + V_1 \psi^* \quad \checkmark$$