

# 11.10 LS - Coupling:

Important example: adding orbital angular momentum and spin  $1/2$

$$j_1 = l \text{ (integer)}, m_1 = m_l$$

$$j_2 = s = \frac{1}{2}, m_2 = m_s = \pm \frac{1}{2}$$

allowed values of  $j$

1)  $l=0: j=1/2$

2)  $l > 0: j = l \pm 1/2$

example: p-state  $\hat{=} l=1$

$\Rightarrow j = 1/2, j = 3/2 \Rightarrow$

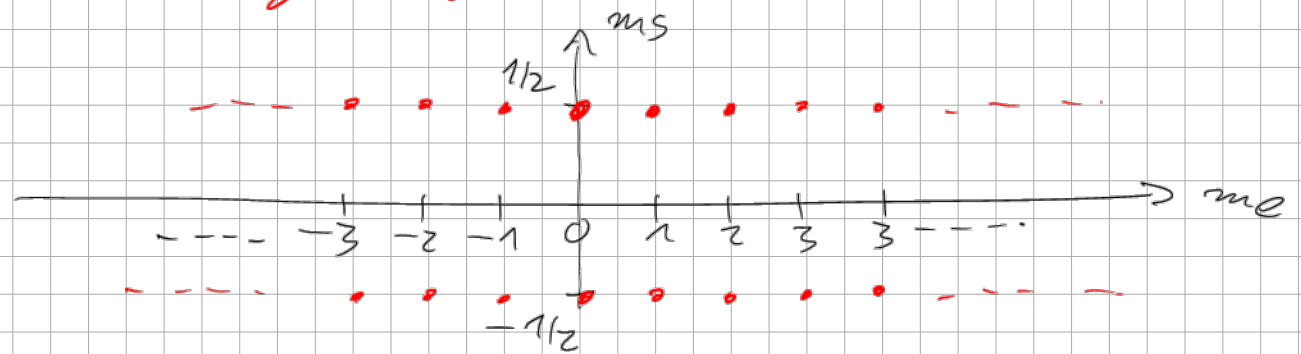
$l=1$

$P^{1/2}, P^{3/2}$   
subscript to  $j$

$m_l, m_s$  - plane is

particularly simple:

two rows corresponding to  $m_s = \pm 1/2$



concentrate on  $j = l + 1/2$  ( $l > 0$ ):

$$\hat{j}_- | \underbrace{l + \frac{1}{2}}_{=j}, \underbrace{m+1}_{=m_j} \rangle = \hbar \sqrt{\underbrace{(l + \frac{1}{2} + m + 1)}_{=j} \underbrace{(l + \frac{1}{2} - m - 1 + 1)}_{=j} \underbrace{(l + \frac{1}{2} - m - 1 + 1)}_{=-m_j}} | \underbrace{l + \frac{1}{2}}_{=j}, m \rangle$$

$$= (\hat{L}_- + \hat{S}_-) | \underbrace{m_l}_{=m_l}, \underbrace{m_s}_{=m_s} \rangle = \sum_{\substack{m_l', m_s' \\ m_l' + m_s' = m+1}} | \underbrace{m_l'}_{=m_l'}, \underbrace{m_s'}_{=m_s'} \rangle \langle m_l', m_s' | l + \frac{1}{2}, m+1 \rangle$$

$$= \sum_{m_l', m_s'} \hbar \sqrt{(l + m_l')(l - m_l' + 1)} | \underbrace{m_l' - 1}_{=m_l'}, m_s' \rangle \langle m_l', m_s' | l + \frac{1}{2}, m+1 \rangle \quad (1)$$

$$m+1 = m_e' + m_s'$$

$$+ \sqrt{\left(\frac{1}{2} + m_s'\right)\left(\frac{1}{2} - m_s' + 1\right)} |m_e', m_s' - 1\rangle \langle m_e' m_s' | l + \frac{1}{2}, m+1 \rangle \quad (2)$$

Apply  $\langle m_e, m_s \rangle$  to this equation:

(1)  $m_e = m_e' - 1, m_s = m_s' \Rightarrow m_e' = m_e + 1, m_s' = m_s$ ;  $m+1 = m_e' + m_s' = m_e + 1 + m_s$

(2)  $m_e = m_e', m_s = m_s' - 1 \Rightarrow m_e' = m_e, m_s' = m_s + 1$ ;  $m+1 = m_e' + m_s' = m_e + m_s + 1$

choice:  $m_e = m - \frac{1}{2}, m_s = \frac{1}{2} \Rightarrow m = m_e + m_s \checkmark \Rightarrow m = m_e + m_s$

(1)  $m_e' = m_e + 1 = m + \frac{1}{2}, m_s' = m_s = \frac{1}{2}$

(2)  $m_e' = m_e = m - \frac{1}{2}, m_s' = m_s + 1 = \frac{3}{2}$

$$\sqrt{\left(l + m + \frac{3}{2}\right)\left(l - m + \frac{1}{2}\right)} \langle m - \frac{1}{2}, \frac{1}{2} | l + \frac{1}{2}, m \rangle$$

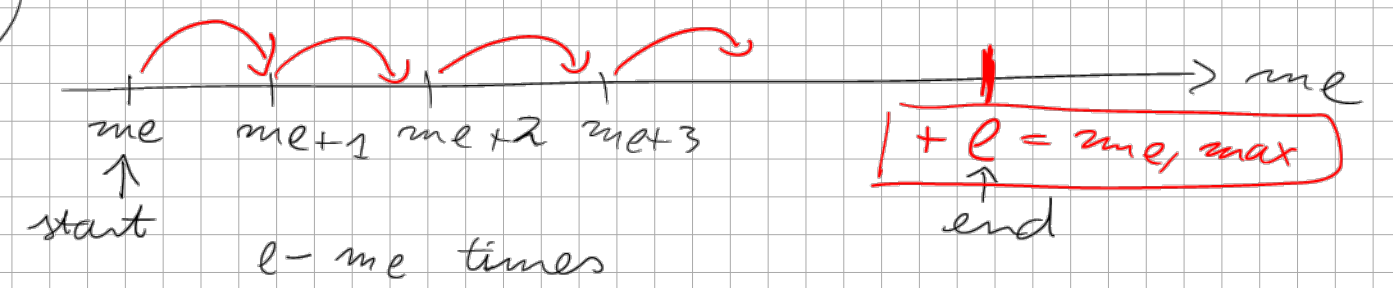
$$= \sqrt{\left(l + m + \frac{1}{2}\right)\left(l - m - \frac{1}{2} + 1\right)} \underbrace{\langle m - \frac{1}{2}, \frac{1}{2} | m - \frac{1}{2}, \frac{1}{2} \rangle}_{=1} \langle m + \frac{1}{2}, \frac{1}{2} | l + \frac{1}{2}, m+1 \rangle \quad (1)$$

~~$$+ \sqrt{\left(\frac{1}{2} + \frac{3}{2}\right)\left(\frac{1}{2} - \frac{3}{2} + 1\right)} \underbrace{\langle m - \frac{1}{2}, \frac{1}{2} | m - \frac{1}{2}, \frac{3}{2} - 1 \rangle}_{=1} \underbrace{\langle m - \frac{1}{2}, \frac{3}{2} | l + \frac{1}{2}, m+1 \rangle}_{m_s = m_s}$$~~

$$\langle \underbrace{m - \frac{1}{2}}_{=m_e}, \underbrace{\frac{1}{2}}_{=m_s} | l + \frac{1}{2}, m \rangle = \sqrt{\frac{l + m + \frac{1}{2}}{l + m + \frac{3}{2}}} \langle \underbrace{m + \frac{1}{2}}_{m_e + 1}, \frac{1}{2} | l + \frac{1}{2}, m+1 \rangle \quad (*)$$

$$\Rightarrow m = m_e + \frac{1}{2}$$

$$m_s = \frac{1}{2}$$



$l - m_e$  times

$$\hat{=} l - m_e = l + \frac{1}{2} - (m_e + \frac{1}{2}) = l + \frac{1}{2} - m \text{ iterations}$$

$$= \sqrt{\frac{l+m+\frac{1}{2}}{l+m+\frac{3}{2}}} \cdot \sqrt{\frac{l+m+\frac{3}{2}}{l+m+\frac{5}{2}}} \quad \langle m+\frac{3}{2}, \frac{1}{2} | l+\frac{1}{2}, m+2 \rangle$$

$$= \dots = \sqrt{\frac{l+m+\frac{1}{2}}{l+m+\frac{1}{2} + l+\frac{1}{2} - m}} \quad \langle m-\frac{1}{2} + l+\frac{1}{2} - m, \frac{1}{2} | l+\frac{1}{2}, m+l+\frac{1}{2} - m \rangle$$

$$= \sqrt{\frac{l+m+\frac{1}{2}}{2l+1}} \quad \langle \underbrace{l}_{m_e, \max}, \underbrace{\frac{1}{2}}_{m_s, \max} | \underbrace{l+\frac{1}{2}}_{=j}, \underbrace{l+\frac{1}{2}}_{=m_j, \max} \rangle$$

$$| \underbrace{l}_{m_e, \max}, \underbrace{\frac{1}{2}}_{m_s, \max} \rangle \equiv | \underbrace{l+\frac{1}{2}}_j, \underbrace{l+\frac{1}{2}}_{=m_j, \max} \rangle \Rightarrow \langle l, \frac{1}{2} | l+\frac{1}{2}, l+\frac{1}{2} \rangle \equiv 1$$

$$\langle m-\frac{1}{2}, \frac{1}{2} | l+\frac{1}{2}, m \rangle = \sqrt{\frac{l+m+\frac{1}{2}}{2l+1}}$$

This result is 1/4 of the whole story:

$$| j = l + \frac{1}{2}, m \rangle = \sqrt{\frac{l+m+\frac{1}{2}}{2l+1}} | \underline{m_e = m - \frac{1}{2}}, \underline{m_s = \frac{1}{2}} \rangle + \otimes | \underline{m_e = m + \frac{1}{2}}, \underline{m_s = -\frac{1}{2}} \rangle$$

$$|j = l - \frac{1}{2}, m\rangle = \textcircled{*} |m = m - \frac{1}{2}, m_s = \frac{1}{2}\rangle + \textcircled{*} |m = m + \frac{1}{2}, m_s = -\frac{1}{2}\rangle$$

$$\begin{pmatrix} |l + \frac{1}{2}, m\rangle \\ |l - \frac{1}{2}, m\rangle \end{pmatrix} = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} \underbrace{\begin{pmatrix} |m - \frac{1}{2}, \frac{1}{2}\rangle \\ |m + \frac{1}{2}, -\frac{1}{2}\rangle \end{pmatrix}}_{m, m_s \text{-basis states}}$$

$j, m$ -basis states    orthogonal transformation

$$\cos \alpha = \sqrt{\frac{l + m + 1/2}{2l + 1}} \Rightarrow \sin \alpha = \pm \sqrt{1 - \cos^2 \alpha} = \pm \sqrt{\frac{l - m + 1/2}{2l + 1}}$$

$$\Rightarrow \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{l + m + 1/2}{2l + 1}} & \sqrt{\frac{l - m - 1/2}{2l + 1}} \\ -\sqrt{\frac{l - m + 1/2}{2l + 1}} & \sqrt{\frac{l + m + 1/2}{2l + 1}} \end{pmatrix}$$

Spinorial spherical harmonics:

$$|Y_{l, \frac{1}{2}}^{j=l \pm \frac{1}{2}, m}\rangle = \pm \sqrt{\frac{l \pm m + 1/2}{2l + 1}} |m - \frac{1}{2}, \frac{1}{2}\rangle + \sqrt{\frac{l \mp m + 1/2}{2l + 1}} |m + \frac{1}{2}, -\frac{1}{2}\rangle$$

$$|m, l, \frac{1}{2}\rangle \hat{=} Y_l^m(\vartheta, \varphi) \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |m, l, -1/2\rangle = Y_l^m(\vartheta, \varphi) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$Y_{l, \frac{1}{2}}^{j=l \pm \frac{1}{2}, m}(\vartheta, \varphi) = \pm \sqrt{\frac{l \pm m + 1/2}{2l + 1}} Y_l^{m - \frac{1}{2}}(\vartheta, \varphi) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \sqrt{\frac{l \mp m + 1/2}{2l + 1}} Y_l^{m + \frac{1}{2}}(\vartheta, \varphi) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Later application:

- 1) fine structure
- 2) Zeeman effect, Landé factor

} important for understanding

3) solving Dirac equation for hydrogen atom

atomic physics

11.11 Fine structure of Hydrogen structure:

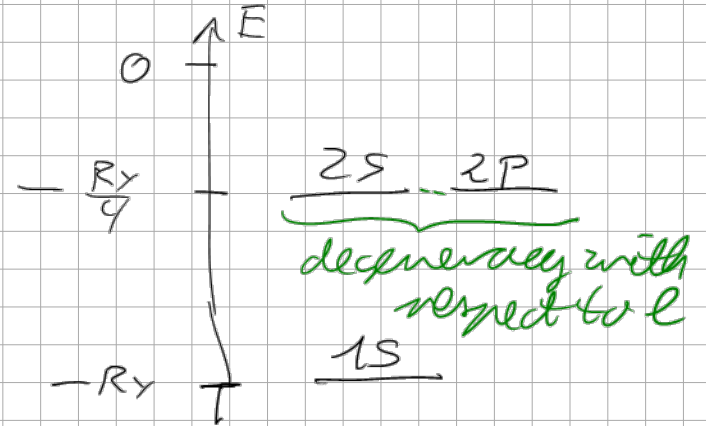
Lecture QM1 deals with non-relativistic hydrogen atom

$$\hat{H}_0 = \frac{\vec{p}^2}{2m} - \frac{e^2}{4\pi\epsilon_0 r}$$

$$E_n^{(0)} = -Ry \frac{1}{n^2}, \quad Ry = \frac{1}{2} Mc^2 \alpha^2 = 13.6 \text{ eV}$$

$$\alpha \approx \frac{1}{137}$$

0.5 MeV



Now: special relativistic corrections

There are now 3 different special relativistic corrections, which sum up to the fine structure correction, determined by Dirac theory

11.11.1 Correction of Kinetic Energy:

$$T = \sqrt{\vec{p}^2 c^2 + M^2 c^4} = Mc^2 \left\{ 1 + \frac{\vec{p}^2}{M^2 c^2} \right\}^{1/2} \stackrel{|\vec{p}| \ll Mc}{\approx} Mc^2 \left\{ 1 + \frac{1}{2} \frac{\vec{p}^2}{M^2 c^2} + \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{\vec{p}^4}{M^2 c^2} + \dots \right\}$$

$$= \underbrace{Mc^2}_{\text{rest energy}} + \underbrace{\frac{\vec{p}^2}{2m}}_{\text{non-relativistic limit}} - \underbrace{\frac{\vec{p}^4}{8M^3 c^2}}_{\text{relativistic correction}} + \dots$$

The consequences of this relativistic correction of kinetic energy was calculated on Problem Set 2. due to perturbation theory based

on Feynman - Hellmann theory:

$$E_{kE} = E_n^{(0)} \alpha^2 \left\{ \frac{1}{n \left( l + \frac{1}{2} \right)} - \frac{3}{4n^2} \right\}$$

↑ lifts degeneracy of  $E_n^{(0)}$  with respect to  $l$

⇒ But spin of electron yields another special relativistic correction

### 11.11.2 Spin-Orbit Coupling:

According to Dirac theory the electron spin leads to a magnetic moment

$$\vec{\mu} = -\mu_B g_S \frac{\vec{S}}{\hbar}$$

Bohr magneton:  $\mu_B = \frac{e \hbar}{2m}$

$$\vec{\mu} = -\frac{e}{m} \vec{S}$$

Landé factor:  $g_S = 2$

• Electron at rest:  $\vec{E} = -\vec{\nabla} \varphi, \quad \varphi = -\frac{e}{4\pi\epsilon_0 r}$

• Electron moving with velocity  $\vec{v} = \frac{\vec{p}}{m}$  sees in addition a magnetic field

$$\vec{B} = \frac{\vec{v}}{c^2} \times \vec{E} \quad \left( \frac{|\vec{v}|}{c} \ll 1 \right)$$

Energy correction:

$$-\vec{\mu} \cdot \vec{B} = \frac{e}{m} \vec{S} \cdot \vec{B} = \frac{e}{mc^2} \vec{S} \cdot (\vec{v} \times \vec{E}) = \frac{e}{m^2 c^2} \vec{S} \cdot (\vec{p} \times \vec{E})$$

$$= -\frac{e}{m^2 c^2} \vec{S} \cdot (\vec{p} \times \vec{\nabla} \varphi) \quad \text{with} \quad \vec{\nabla} = \vec{e}_r \frac{\partial}{\partial r} = \frac{\vec{x}}{r} \frac{\partial}{\partial r}$$

$$= \frac{e}{m^2 c^2} \frac{1}{r} \frac{\partial \varphi}{\partial r} (\vec{x} \times \vec{p}) \cdot \vec{S} = \frac{e}{m^2 c^2} \frac{1}{r} \frac{\partial \varphi}{\partial r} \vec{L} \cdot \vec{S}$$

A factor 2 is wrong here due to Thomas precession

$$\vec{H}_{so} = \frac{e}{4\pi\epsilon_0} \frac{1}{2m^2 c^2} \frac{\partial \varphi}{\partial \vec{r}} \vec{L} = \vec{S} = \frac{e^2}{8\pi\epsilon_0} \frac{1}{m^2 c^2} \boxed{\vec{L} \cdot \vec{S}}$$