

2.3 Geodetic Precession:

precession of spinning top
freely falling in a gravita-
tional field

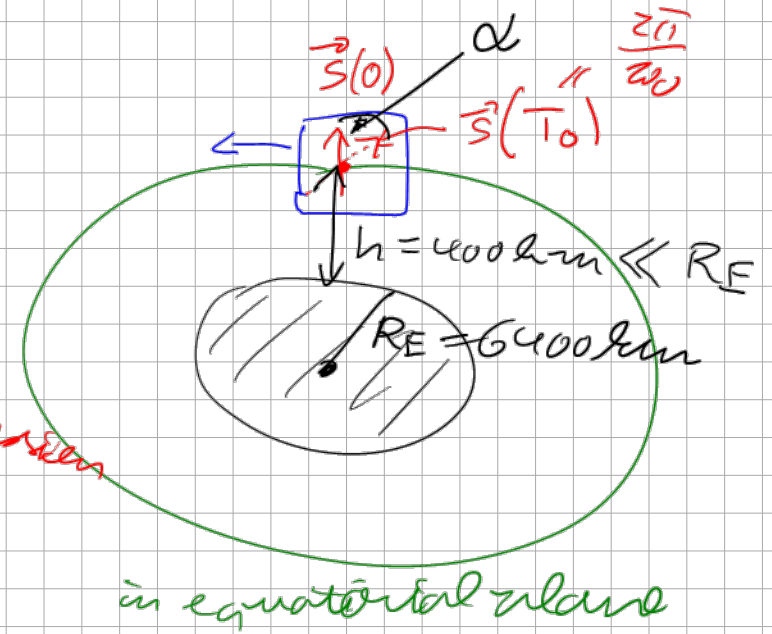
geodetic equations

$$\frac{d^2 x^\mu}{d\tau^2} = -\Gamma_{\mu\nu}^\lambda \frac{dx^\nu}{d\tau} \frac{dx^\lambda}{d\tau} \quad (1)$$

spin precession

$$\frac{ds^\mu}{d\tau} = -\Gamma_{\mu\nu}^\lambda s^\nu \frac{dx^\lambda}{d\tau}$$

center-of-mass
affects spin precession



$$(x^0(\tau), r(\tau), \vartheta(\tau), \varphi(\tau)) \\ \approx (\underline{u^0 \tau}, \underline{r}, \underline{\frac{\pi}{2}}, \underline{\omega_0 \tau})$$

$$\left\{ \begin{array}{l} s^2(\tau) = 0 \Rightarrow \text{spin vector in equatorial plane} \\ \frac{d^2 s^\mu}{d\tau^2} + \omega^2 s^\mu = 0, \quad \omega \approx \omega_0 \left[1 - \left(\gamma + \frac{1}{2} \right) \frac{GM}{c^2 r} + \dots \right] \end{array} \right.$$

leading difference
is due to gravities

$$\Rightarrow \omega < \omega_0$$

$$g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = c^2 \quad (2) \quad g_{\mu\nu} s^\mu s^\nu = -s^2$$

$$g_{\mu\nu} \frac{dx^\mu}{d\tau} s^\nu = 0$$

$$(1) \left(\frac{u^0}{\omega_0} \right)^2 = \frac{r^2}{B(r)}$$

$$(2) B(r) (u^0)^2 - r^2 (\omega_0)^2 = c^2$$

$$\Rightarrow \omega_0^2 \approx \frac{GM}{R_E^3} \quad \begin{array}{l} \text{gravitational force} \\ = \text{centrifugal force} \end{array}$$

$$\begin{aligned}
 & (s^0(0), s^1(0), s^2(0), s^3(0)) = (0, s, 0, 0) \\
 & \downarrow \\
 & (s^0(\tau), s^1(\tau), s^2(\tau), s^3(\tau)) \\
 & = \left(-\frac{\beta^i(\nu) a_0}{2\beta(\nu) \omega} s \sin \omega \tau, \underbrace{s \cos \omega \tau, 0, -\frac{\omega_0}{2\omega} s \sin \omega \tau}_{\hat{=} \text{precession of spin in equatorial plane}} \right)
 \end{aligned}$$

$s^1 = s^2$ $s^2 = s^3$ $s^3 = s^4$

2.3.4 Physical Interpretation:

Angle between spin vectors $(s^i(0))$ and $(s^i(\tau_0))$ in equatorial plane

$$\begin{aligned}
 -\cos \alpha &= \frac{g_{ij} s^i(\tau=0) s^j(\tau=\frac{2\pi}{\omega_0})}{\sqrt{g_{ij} s^i(\tau=0) s^j(\tau=0) g_{kl} s^k(\frac{2\pi}{\omega_0}) s^l(\frac{2\pi}{\omega_0})}} = -\cos \left(2\pi \frac{\omega}{\omega_0} \right) \\
 & \qquad \qquad \qquad \text{ratio of two angular frequencies}
 \end{aligned}$$

• $A(\nu) = B(\nu) = 1$: $\omega = \omega_0 \Rightarrow \alpha = 2\pi$

• $A(\nu), B(\nu) \neq 1$:

$$\Delta \alpha = 2\pi \frac{\omega}{\omega_0} - 2\pi = \underbrace{-3\pi}_{\substack{\uparrow \\ \text{spin lags behind}}} \frac{6M}{c^2 r} \frac{1+2\gamma}{3}$$

spin lags behind

$$|\Delta \alpha| = 3\pi \frac{4.6 \cdot 10^{-3}}{6.4 \cdot 10^6} \frac{360 \cdot 3600}{2\pi} = 1.4 \cdot 10^{-3} \text{ ''}$$

one year observation:

$$\frac{\Delta t}{T_0} = \frac{365 \cdot 24}{1.4} = 6257$$

$$|\Delta \alpha|_{\text{to E}} = 6257 \cdot 1.4 \cdot 10^{-3}'' = 8.8'' \quad (\text{per year})$$

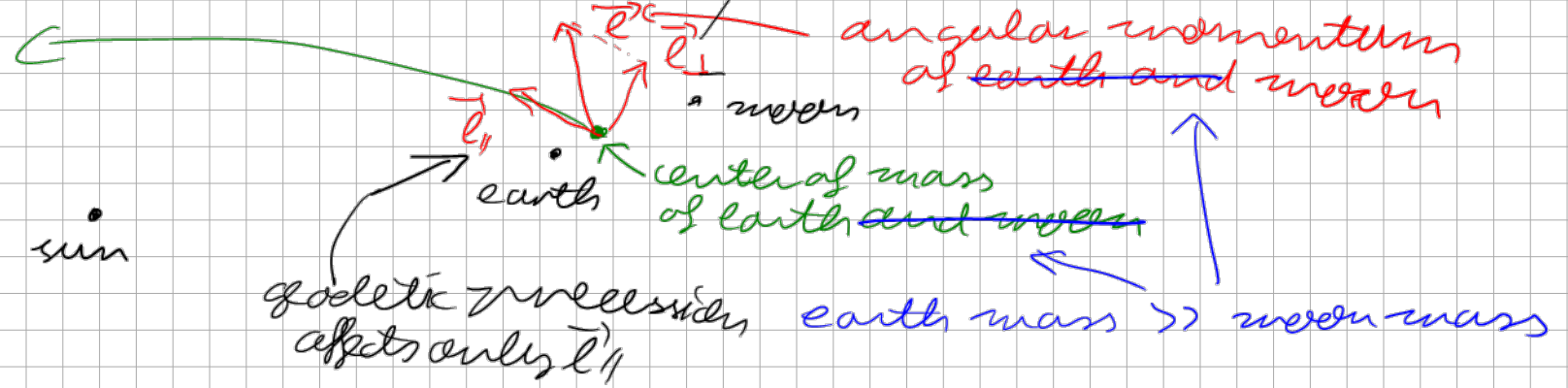
2.3.5 Gravity Probe B Experiment:

- satellite mission = test prediction of GR
- NASA and Stanford University (Francis Everitt)
- costs = 1 billion dollar
- 4 spinning tops: gyroscopes
 - > quartz sphere of size of a tennis ball (3.8 cm)
 - > in vacuum = 10,000 rotations per minute
 - > cooled down to 1.8 K: surface made of Niobium, is superconducting
 - > changes of rotation axis measurable via SQUIDS
 - > accuracy: they claim to measure changes of $1/40,000,000^\circ = 0.032 \mu''$
comparison: resolve a pinhead at a distance of 1000 km
- mission beginning = 2004
- April 14, 2007: Spring Conference APS
 - geodetic effect confirmed with a precision as better than 1%

cooling with ^4He
(theoretical limit
of cooling is 0.7 K)

2.3.6 de Sitter Precession of Moon:

\hat{s}^2 does not change
↑



moon motion plane is rotated only 5° with respect to earth motion plane:
 \vec{l}_\perp large, \vec{l}_\parallel small

\Rightarrow geodetic precession yields a small rotation of moon motion plane with respect to earth motion plane

$$|\Delta\alpha| = 3\pi \frac{1.5}{15 \cdot 10^8} \cdot \frac{360 \cdot 3600^\circ}{2\pi} = 0.02''$$

per century : $2''$ (prediction from de Sitter, 1916)

All other planets in our solar system also lead to geodetic precessions of earth-moon system : 10^7 larger

only possible provided that moon orbit is precisely known

1969: Apollo mission, mirrors installed, distance between earth and moon detectable

\Rightarrow precession of moon-motion was deduced a precision of 0.7 %.

2.4 Lense-Thirring Effect:

Precession of spinning ^{top} due to the rotation of a gravitational field
⇒ quite small: magnitude 1/100 times smaller than geodetic precession for experimental detection

2.4.1 Kerr Metric:

static gravitational field of mass M and angular momentum L

$$ds^2 = \left(1 - \frac{2az}{s^2}\right) c^2 dt^2 + 4ab \frac{2\sin^2\vartheta}{s^2} c dt d\varphi$$

Note: rotation axis is z-axis

$$- \frac{s^2}{\Delta} dr^2 - s^2 d\vartheta^2 - \sin^2\vartheta \left(r^2 + b^2 + \frac{2az}{s^2} b^2 \sin^2\vartheta \right) d\varphi^2$$

$$s^2 = r^2 + b^2 \cos^2\vartheta, \quad \Delta = r^2 - 2az + b^2$$

$$a = \frac{GM}{c^2}, \quad b = \frac{L}{cM}$$

We are looking for the leading correction to Schwarzschild metric

$$ds^2 = ds_{SS}^2 + \left[4ab \frac{\sin^2\vartheta}{r^2} (c dt)(r d\varphi) \right] + \mathcal{O}(b^2)$$

leading term

subleading term
first correction due to L

What is the order of magnitude of that correction?

$$L \sim I \Omega \quad I \sim MR^2 \quad V = R\Omega$$

$$\boxed{} \sim \underbrace{\frac{GM}{c^2}}_a \cdot \frac{1}{cM} \cdot \cancel{M} R V \quad \frac{1}{R^2} = \underbrace{\frac{a}{R}}_{\text{mass effect}} \underbrace{\frac{V}{c}}_{\text{angular momentum effect}}$$

2.4.2 Cartesian Coordinates:

$$\left. \begin{aligned} x &= r \sin \vartheta \cos \varphi \\ y &= r \sin \vartheta \sin \varphi \\ z &= r \cos \vartheta \end{aligned} \right\} \tan \varphi = \frac{y}{x}$$

$$\Rightarrow d\varphi = \cos^2 \varphi \left(\frac{dy}{x} - \frac{y}{x^2} dx \right)$$

$$ds^2 = ds_{SS}^2 + 4 \cdot ab \frac{\cancel{\sin^2 \vartheta}}{r^2} \frac{x^2}{r^2 \cancel{\sin^2 \vartheta}} \left(\frac{dy}{x} - \frac{y}{x^2} dx \right) (cdt)$$

$$= ds_{SS}^2 + 4 \frac{GM}{c^2} \frac{L}{cM} \cdot \frac{1}{r^3} (x dy - y dx) c dt + \dots$$

$$L = I \Omega, \quad I = \frac{2}{5} M R_E^2$$

$$ds^2 = ds_{SS}^2 + 4 \frac{G}{c^3} \frac{2}{5} M R_E^2 \frac{x dy - y dx}{r^3} R c dt + \dots$$

$$\vec{r} = r \vec{e}_z, \quad \vec{r} \times \vec{v} = r \begin{pmatrix} -y \\ x \\ 0 \end{pmatrix}$$

$$(\vec{r} \times \vec{v}) \cdot d\vec{v} = -r \boxed{(y dx - x dy)}$$

$$ds^2 = ds_{\text{flat}}^2 - \frac{8GMRE^2}{5c^3} \frac{\vec{r} \times \vec{v}}{r^3} \cdot d\vec{v} \, cd t + \dots$$

Here this was determined from Kerr metric by perturbation theory. Last exercise sheet in last semester: This was obtained by perturbatively solving Einstein field equations.

2.4.3 Christoffel symbols:

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu + \text{connection in } a + 2 h_{0i} dx^i \, cd t + \dots$$

$$\vec{h} = (h_{0i}), \quad h_{0i} = -\frac{4GMRE^2}{5c^3} \epsilon_{imn} \frac{r_m \times v_n}{r^3}$$

$$(g_{\mu\nu}) = \begin{pmatrix} g_{00} & g_{0i} \\ g_{i0} & g_{ij} \end{pmatrix} = \begin{pmatrix} 1 & h_{0i} \\ h_{0i} & -\delta_{ij} \end{pmatrix}$$

$$\Gamma_{\mu\nu\lambda} = \frac{1}{2} (\partial_\lambda g_{\mu\nu} + \partial_\mu g_{\nu\lambda} - \partial_\nu g_{\lambda\mu})$$

$$\Gamma_{0i\gamma} = \Gamma_{i0\gamma} = \frac{1}{2} (\partial_i h_{0\gamma} - \partial_\gamma h_{0i}) + \dots$$

$$\Gamma_{i\gamma 0} = \Gamma_{\gamma i 0} = \frac{1}{2} (\partial_i h_{0\gamma} + \partial_\gamma h_{0i}) + \dots$$

$$(g^{\mu\nu}) = \begin{pmatrix} 1 & h_{0i} \\ h_{0i} & -\delta_{ij} \end{pmatrix} + \dots$$

$$\Gamma_{\lambda\mu}^\alpha = g^{\alpha\gamma} \Gamma_{\lambda\mu\gamma}$$

all derivatives with respect to time vanish as we deal with a stationary gravitational field

~~geodesic precession~~ ✓

Lense-Thirring effect

$$\Gamma_{i0}^j = \Gamma_{0i}^j = -\Gamma_{0i5} + \dots = \frac{1}{2} (\partial_j h_{0i} - \partial_i h_{0j}) + \dots$$

$$\Gamma_{i5}^0 = \Gamma_{5i}^0 = \Gamma_{i50} + \dots = \frac{1}{2} (\partial_i h_{05} + \partial_5 h_{0i}) + \dots$$

2.4.4 Spin Precession:

$$\frac{d^2 x^\lambda}{d\tau^2} = -\Gamma_{\mu\nu}^\lambda \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}, \quad \frac{ds^\lambda}{d\tau} = -\Gamma_{\mu\nu}^\lambda s^\mu \frac{dx^\nu}{d\tau}$$

first order in h
 $\sim \Omega \Rightarrow$ small

center-of-mass motion affects the spin motion

center of mass motion enters only in zeroth order

$$\Rightarrow (x^\lambda) = (c\tau, 0, 0, 0), \quad (u^\lambda) = \left(\frac{dx^\lambda}{d\tau} \right) = (c, 0, 0, 0)$$

$$\frac{d^2 x^0}{d\tau^2} = -\Gamma_{\mu\nu}^0 \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = -\Gamma_{i5}^0 \frac{dx^i}{d\tau} \frac{dx^5}{d\tau} \quad \checkmark$$

$$\frac{d^2 x^i}{d\tau^2} = -\Gamma_{\mu\nu}^i \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = (\Gamma_{50}^i c + \Gamma_{05}^i c) \frac{dx^5}{d\tau} \frac{dx^0}{d\tau} \quad \checkmark$$

} $\tau = t$

TO DO: solve spin equation \Rightarrow precession of spin