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ABSTRACT. In this article we present a parallel modular algorithm to compute all solutions with multiplicities of a given zero-dimensional polynomial system of equations over the rationals. In fact, we compute a triangular decomposition using Möller's algorithm (cf. [Mö93]) of the corresponding ideal in the polynomial ring over the rationals using modular methods, and then apply a solver for univariate polynomials.

1. INTRODUCTION

One possible approach¹ to find the solutions of a zero-dimensional system of multivariate polynomials is the triangular decomposition of the corresponding ideal since triangular systems of polynomials can be solved using a univariate solver recursively. There are already several results in this direction including an implementation in *Maple* (cf. [AM99], [LMX05], [Ma00]). The technique to compute triangular sets has been refined (cf. [DMSWX05], [CLMPX07], [LMX06]), modularized and parallelized (cf. [MX07], [LM07]). We report about a modular and parallel version of the solver in SINGULAR (cf. [DGPS12]) and focus mainly on a probabilistic algorithm to compute the solutions of a polynomial system with multiplicities.

2. Preliminary technicalities

We recall the definition and some properties of a triangular decomposition. For details we refer to [GP07], [Mö93] and [Mö97].

Let K be a field, $X = \{x_1, \ldots, x_n\}$ a set of variables, $I \subseteq K[X]$ a zerodimensional ideal, and we fix > to be the lexicographical ordering induced by $x_1 > \ldots > x_n$. If $f \in K[X]$ is a polynomial, then we denote by LE(f) the leading exponent of f, by LC(f) the leading coefficient of f, by LM(f) the leading monomial of f, and by $LT(f) = LC(f) \cdot LM(f)$ the leading term of f.

Definition 2.1. A set of polynomials $F = \{f_1, \ldots, f_n\} \subseteq K[X]$ is called a *trian*gular set if $LT(f_i) = x_{n-i+1}^{\alpha_i}$ for some $\alpha_i > 0$ and each i = 1, ..., n. A list $\mathcal{F} = (F_1, ..., F_s)$ of triangular sets is called a *triangular decomposition* of

a zero-dimensional ideal $I \subseteq K[X]$ if $\sqrt{I} = \sqrt{\langle F_1 \rangle} \cap \ldots \cap \sqrt{\langle F_s \rangle}$.

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¹In SINGULAR (cf. [DGPS12]) this approach is implemented in the library solve.lib on the basis of an univariate Laguerre solver (cf. [RR78, §8.9-8.13]).

Remark 2.2.

- (1) A triangular set is a Gröbner basis.
- (2) A minimal Gröbner basis of a maximal ideal is a triangular set, and the primary decomposition of \sqrt{I} is a triangular decomposition of I.

The following two lemmata are the basis for the algorithm by Möller (cf. [Mö93]) which avoids primary decomposition.

Lemma 2.3. Let $G = \{g_1, \ldots, g_m\}$ be a reduced Gröbner basis of the zero-dimensional ideal $I \subseteq K[X]$ such that $LM(g_1) < \ldots < LM(g_m)$. Moreover, for $i = 1, \ldots, m$, let $\alpha_i = LE(g_i)$ in $(K[x_2, \ldots, x_n])[x_1]$, i.e. $g_i = \sum_{j=0}^{\alpha_i} g'_{ij} x_1^j$ for suitable $g'_{ij} \in K[x_2, \ldots, x_n]$. Then $G' = \{g'_{1\alpha_1}, \ldots, g'_{m-1\alpha_{m-1}}\}$ is a Gröbner basis of $\langle g_1, \ldots, g_{m-1} \rangle : g_m$, and we have $\langle G', g_m \rangle = \langle G', G \rangle$.

Proof. The proof can be found in [Mö93, Lemma 7].

Lemma 2.4. Let $I \subseteq K[X]$ be a zero-dimensional ideal, and $h \in K[X]$. Then the following hold.

- (1) $\sqrt{I} = \sqrt{\langle I, h \rangle} \cap \sqrt{I:h}.$
- (2) $\dim_K \left(K[X]/I \right) = \dim_K \left(K[X]/\langle I,h \rangle \right) + \dim_K \left(K[X]/(I:h) \right).$

Proof.

- (1) The proof is an exercise in [GP07, Exercise 4.5.3].
- (2) We consider two exact sequences. The first one

$$0 \longrightarrow (I:h)/I \longrightarrow K[X]/I \xrightarrow{\cdot h} K[X]/I \longrightarrow K[X]/\langle I,h\rangle \longrightarrow 0$$

yields $\dim_K ((I:h)/I) = \dim_K (K[X]/\langle I,h\rangle)$, and the second one

$$0 \longrightarrow (I:h)/I \longrightarrow K[X]/I \longrightarrow K[X]/(I:h) \longrightarrow 0$$

yields $\dim_K (K[X]/I) = \dim_K ((I:h)/I) + \dim_K (K[X]/(I:h))$. Summarized, we obtain

$$\dim_K \left(K[X]/I \right) = \dim_K \left(K[X]/\langle I, h \rangle \right) + \dim_K \left(K[X]/(I:h) \right).$$

Consequently, for $h_1, \ldots, h_l \in K[X]$ and $h_{l+1} = 1$, we are able to apply Lemma 2.4 inductively and obtain

$$\begin{split} \sqrt{I} &= \sqrt{\langle I, h_1 \rangle} \cap \sqrt{I : h_1} \\ &= \sqrt{\langle I, h_1, h_2 \rangle} \cap \sqrt{\langle I, h_1 \rangle : h_2} \cap \sqrt{I : h_1} \\ &= \dots \\ &= \sqrt{\langle I, h_1, \dots, h_l \rangle} \cap \left(\bigcap_{i=1}^{l+1} \sqrt{\langle I, h_1, \dots, h_{i-1} \rangle : h_i} \right). \end{split}$$

Together with Lemma 2.3 we conclude the following corollary.

Corollary 2.5. With the assumption of Lemma 2.3, let $G' \setminus G = \{h_1, \ldots, h_l\}$. Then the following hold.

- (1) If $G' \smallsetminus G \neq \emptyset$, then $I \subsetneq \langle G, h_1 \rangle$ and $I \subsetneq \langle G \rangle : h_1$.
- (2) $\sqrt{I} = \sqrt{\langle G', g_m \rangle} \cap \left(\bigcap_{i=1}^{l+1} \sqrt{\langle G, h_1, \dots, h_{i-1} \rangle : h_i} \right)$ and, in addition, $I \subseteq \langle G', g_m \rangle \cap \left(\langle G, h_1, \dots, h_{i-1} \rangle : h_i \right).$

(3)
$$\dim_K (K[X]/I) = \sum_{i=1}^{l+1} \dim_K (K[X]/(\langle G, h_1, \dots, h_{i-1} \rangle : h_i)).$$

With regard to Corollary 2.5(2), especially $\langle G, h_1, \ldots, h_l \rangle = \langle G', g_m \rangle$ with $G' \subseteq K[x_2, \ldots, x_n]$ is predestined for induction since $\sqrt{\langle G', g_m \rangle} = \sqrt{\langle F'_1, g_m \rangle} \cap \ldots \cap \sqrt{\langle F'_s, g_m \rangle}$ if $\mathcal{F}' = (F'_1, \ldots, F'_s)$ is a triangular decomposition of G'. Referring to Corollary 2.5(3), the triangular decomposition obtained by iterating the approach of Corollary 2.5 respects the multiplicities of the zeros of I. Therefore the zerosets of different triangular sets are in general not disjoint as the following example shows.

Example 2.6. Let $G = \{x_2^{10}, x_1x_2^3 + x_2^5, x_1^{11}\} \subseteq \mathbb{Q}[x_1, x_2]$. Then we obtain $G' = \{x_2^{10}, x_2^3\}$, $G' \smallsetminus G = \{x_2^3\}$, and the triangular decomposition $\mathcal{F} = (F_1, F_2)$ of $\langle G \rangle$ with $F_1 = \langle G \rangle : x_2^3 = \langle x_2^7, x_1 + x_2^2 \rangle$ and $F_2 = \langle G, x_2^3 \rangle = \langle x_2^3, x_1^{11} \rangle$. Moreover, it holds $\dim_{\mathbb{Q}}(\mathbb{Q}[x_1, x_2]/\langle G \rangle) = 40$, $\dim_{\mathbb{Q}}(\mathbb{Q}[x_1, x_2]/\langle G \rangle : x_2^3)) = 7$, and $\dim_{\mathbb{Q}}(\mathbb{Q}[x_1, x_2]/\langle G, x_2^3 \rangle) = 33$. Note that $\langle G \rangle \subsetneq F_1 \cap F_2$.

Algorithm 1 shows the algorithm by Möller to compute the triangular decomposition of a zero-dimensional ideal. 2

Algorithm 1 Triangular Decomposition (triangM)
Input: $I \subseteq K[X]$, a zero-dimensional ideal .
Output: $\mathcal{F} = (F_1, \ldots, F_s)$, a triangular decomposition of $I \subseteq K[X]$ such that $\dim_K (K[X]/I) = \sum_{i=1}^s \dim_K (K[X]/\langle F_i \rangle).$
1: compute $G = \{g_1, \ldots, g_m\}$, a reduced Gröbner basis of I with respect to the
lexicographical ordering > such that $LM(g_1) < \ldots < LM(g_m);$
2: compute $G' = \{g'_1, \ldots, g'_{m-1}\} \subseteq K[x_2, \ldots, x_n]$ where g'_i is the leading coefficient
of g_i in $(K[x_2,, x_n])[x_1];$
3: $\mathcal{F}' = \texttt{triangM}(\langle G' \rangle);$
4: $\mathcal{F} = \{F' \cup \{g_m\} \mid F' \in \mathcal{F}'\};$
5: for $1 \le i \le m-1$ do
6: if $g'_i \notin G$ then
7: $\mathcal{F} = \mathcal{F} \cup \texttt{triangM}(\langle G \rangle : g'_i);$
8: $G = G \cup \{g'_i\};$
9: return \mathcal{F} ;

Note that Algorithm 1 is only based on Gröbner basis computations, and does not use random elements. Hence, the result is uniquely determined which allows modular computations. In the following we fix Algorithm 1 to compute a triangular decomposition.

Remark 2.7. Replacing line 7 in Algorithm 1 by $\mathcal{F} = \mathcal{F} \cup \texttt{triangM}(\langle G \rangle : g_i^{\infty})$ we obtain a disjoint triangular decomposition (i.e. $F_i, F_j \in \mathcal{F}$ with $F_i \neq F_j$ implies $\langle F_i \rangle + \langle F_j \rangle = K[X]$). This decomposition does in general not respect the multiplicities (i.e. $\dim_K (K[X]/I) \neq \sum_{i=1}^s \dim_K (K[X]/\langle F_i \rangle))$.

 $^{^2 {\}rm The}$ corresponding procedure is implemented in SINGULAR in the library triang.lib.

3. Modular methods

One possible modular approach for solving a zero-dimensional ideal is to just replace each involved Gröbner basis computation by its corresponding modular algorithm as described in [IPS11]. Particularly, we can replace line 1 in Algorithm 1 by G = modStd(I). In this case it is possible to apply the probabilistic variant since we can easily verify in the end by a simple substitution whether the solutions obtained from the triangular sets are really solutions of the original ideal. Nevertheless, we propose to compute the whole triangular decomposition via modular methods actually. The verification is then similar by just substituting the obtained result into the input polynomials.

We consider the polynomial ring $\mathbb{Q}[X]$, fix a global monomial ordering > on $\mathbb{Q}[X]$, and use the following notation: If $S \subseteq \mathbb{Q}[X]$ is a set of polynomials, then $\mathrm{LM}(S) := \{\mathrm{LM}(f) \mid f \in S\}$ denotes the set of leading monomials of S. If $f \in \mathbb{Q}[X]$ is a polynomial, $I = \langle f_1, \ldots, f_r \rangle \subseteq \mathbb{Q}[X]$ is an ideal, and p is a prime number which does not divide any denominator of the coefficients of f, f_1, \ldots, f_r , then we write $f_p := (f \mod p) \in \mathbb{F}_p[X]$ and $I_p := \langle (f_1)_p, \ldots, (f_r)_p \rangle \subseteq \mathbb{F}_p[X]$.

In the following, $I = \langle f_1, \ldots, f_r \rangle \subseteq \mathbb{Q}[X]$ will be a zero-dimensional ideal. The triangular decomposition algorithm (Algorithm 1) applied to I returns a list of triangular sets $\mathcal{F} = (F_1, \ldots, F_s)$ such that $\sqrt{I} = \bigcap_{i=1}^s \sqrt{\langle F_i \rangle}$ and $\dim_{\mathbb{Q}} (\mathbb{Q}[X]/I) = \sum_{i=1}^s \dim_{\mathbb{Q}} (\mathbb{Q}[X]/\langle F_i \rangle)$.

With respect to modularization, the following lemma obviously holds:

Lemma 3.1. With notation as above, let p be a sufficiently general prime number. Then I_p is zero-dimensional, $((F_1)_p, \ldots, (F_s)_p)$ is a list of triangular sets, and $\sqrt{I_p} = \bigcap_{i=1}^s \sqrt{\langle (F_i)_p \rangle}$.

Relying on Lemma 3.1, the basic idea of the modular triangular decomposition is as follows. First, choose a set \mathcal{P} of prime numbers at random. Second, compute triangular decompositions \mathcal{F}_p of I_p for $p \in \mathcal{P}$. Third, lift the modular triangular sets to triangular sets \mathcal{F} over $\mathbb{Q}[X]$.

The lifting process consists of two steps. First, the set $\mathcal{FP} := \{\mathcal{F}_p \mid p \in \mathcal{P}\}$ is lifted to \mathcal{F}_N with $(F_i)_N \subseteq (\mathbb{Z}/N\mathbb{Z})[X]$ and $N := \prod_{p \in \mathcal{P}} p$ by applying the Chinese remainder algorithm to the coefficients of the polynomials occurring in \mathcal{FP} . Second, we obtain \mathcal{F} with $F_i \subseteq \mathbb{Q}[X]$ by lifting the modular coefficients occurring in \mathcal{F}_p to rational coefficients via the Farey rational map³. This map is guaranteed to be bijective provided that $\sqrt{N/2}$ is larger than the moduli of all coefficients of elements in \mathcal{F} with $F_i \subseteq \mathbb{Q}[X]$.

We now define a property of the set of primes \mathcal{P} which guarantees that the lifting process is feasible and correct. This property is essential for the algorithm.

Definition 3.2. Let $\mathcal{F} = (F_1, \ldots, F_s)$ be the triangular decomposition of the ideal I computed by Algorithm 1.

(1) A prime number p is called *lucky* for I and \mathcal{F} if $((F_1)_p, \ldots, (F_s)_p)$ is a triangular decomposition of I_p . Otherwise p is called *unlucky* for I and \mathcal{F} .

 $^{{}^{3}}Farey$ fractions refer to rational reconstruction. A definition of Farey fractions, the Farey rational map, and remarks on the required bound on the coefficients can be found in [KG83].

(2) A set \mathcal{P} of lucky primes for I and \mathcal{F} is called *sufficiently large* for I and \mathcal{F} if

$$\prod_{p \in \mathcal{P}} p \ge \max\{2 \cdot |c|^2 \mid c \text{ coefficient occuring in } \mathcal{F}\}.$$

From a theoretical point of view, the idea of the algorithm is now as follows: Consider a sufficiently large set \mathcal{P} of lucky primes for I and \mathcal{F} , compute the triangular decomposition of the I_p , $p \in \mathcal{P}$, via Algorithm 1, and lift the results to the triangular decomposition of I as aforementioned.

From a practical point of view, we face the problem that we do not know in advance whether a prime number p is lucky for I and \mathcal{F} .

To handle this problem, we fix a natural number t and an arbitrary set of primes \mathcal{P} of cardinality t. Having computed \mathcal{FP} , we use the following test to modify \mathcal{P} such that all primes in \mathcal{P} are lucky with high probability:

DELETEUNLUCKYPRIMESTRIANG: We define an equivalence relation on $(\mathcal{FP}, \mathcal{P})$ by $(\mathcal{F}_p, p) \sim (\mathcal{F}_q, q) :\iff (\#\mathcal{F}_p = \#\mathcal{F}_q \text{ and } \{\mathrm{LM}(F_p) \mid F_p \in \mathcal{F}_p\} = \{\mathrm{LM}(F_q) \mid F_q \in \mathcal{F}_q\})$. Then the equivalence class of largest cardinality is stored in $(\mathcal{FP}, \mathcal{P})$, the others are deleted.

Since we do not know a priori whether the equivalence class chosen is indeed lucky and whether it is sufficiently large for I and \mathcal{F} , we proceed in the following way. We lift the set \mathcal{FP} to \mathcal{F} over $\mathbb{Q}[X]$ as described earlier, and test the result with another randomly chosen prime number:

PTESTTRIANG: We randomly choose a prime number $p \notin \mathcal{P}$ such that p does not divide the numerator and denominator of any coefficient occuring in a polynomial in $\{f_1, \ldots, f_r\}$ or \mathcal{F} . The test returns true if $(F_p \mid F \in \mathcal{F})$ equals the triangular decomposition \mathcal{F}_p computed by the fixed Algorithm 1 applied on I_p , and false otherwise.

If PTESTTRIANG returns false, then \mathcal{P} is not sufficiently large for I and \mathcal{F} or the equivalence class of prime numbers chosen was unlucky. In this case, we enlarge the set \mathcal{P} by t new primes and repeat the whole process. On the other hand, if PTESTTRIANG returns true, then we have a triangular decomposition \mathcal{F} of I with high probability. In this case, we compute the solutions $S \subseteq \mathbb{C}^n$ with multiplicities of the triangular sets $F = \{f_1, \ldots, f_n\} \in \mathcal{F}$ as follows. Solve the univariate polynomial $f_1(x_1)$ via a univariate solver counting multiplicities, substitute x_1 in $f_2(x_1, x_2)$ by these solutions of $f_1(x_1)$, solve the corresponding univariate polynomial, and continue inductively this way (call this step SOLVETRIANG). Finally, we verify the result $S \subseteq \mathbb{C}^n$ partially by testing whether the original ideal $I \subseteq \mathbb{Q}[X]$ is contained in every $F \in \mathcal{F}$, and whether the sum of the multiplicities equals the \mathbb{Q} -dimension of $\mathbb{Q}[X]/I$ (call this step TESTZERO).

We summarize modular solving in Algorithm 2.⁴

Remark 3.3. In Algorithm 2, the triangular sets \mathcal{F}_p can be computed in parallel. Furthermore, we can parallelize the final verification whether $I \subseteq \mathbb{Q}[X]$ is contained in every $F \in \mathcal{F}$.

 $^{^4}$ The corresponding procedures are implemented in Singular in the library modsolve.lib.

Algorithm 2 Modular Solving (modSolve)

Input: $I \subseteq \mathbb{Q}[X]$, a zero-dimensional ideal. **Output:** $S \subseteq \mathbb{C}^n$, a set of points in \mathbb{C}^n such that f(P) = 0 for all $f \in I, P \in S$. 1: choose \mathcal{P} , a list of random primes; 2: $\mathcal{FP} = \emptyset;$ 3: loop for $p \in \mathcal{P}$ do 4: $\mathcal{F}_p = \texttt{triangM}(I_p)$, the triangular decomposition of I_p via Algorithm 1; 5: $\mathcal{FP} = \mathcal{FP} \cup \{\mathcal{F}_p\};$ 6: $(\mathcal{FP}, \mathcal{P}) = \text{DELETEUNLUCKYPRIMESTRIANG}(\mathcal{FP}, \mathcal{P});$ 7: lift $(\mathcal{FP}, \mathcal{P})$ to \mathcal{F} over $\mathbb{Q}[X]$ by applying Chinese remainder algorithm and 8: Farey rational map; if $PTESTTRIANG(I, \mathcal{F}, \mathcal{P})$ then 9: $S = \text{SOLVETRIANG}(\mathcal{F});$ 10:if TESTZERO (I, \mathcal{F}, S) then 11: 12:return S; enlarge \mathcal{P} ; 13:

4. Examples and timings

In this section we provide examples on which we time the algorithm modSolve (cf. Algorithm 2) and its parallel version as opposed to the algorithm solve (the procedure solve is implemented in SINGULAR in the library solve.lib and computes all roots of a zero-dimensional input ideal using triangular sets). Timings are conducted by using SINGULAR 3-1-6 on an AMD Opteron 6174 machine with 48 CPUs, 2.2 GHz, and 128 GB of RAM running the Gentoo Linux operating system. All examples are chosen from The SymbolicData Project (cf. [G13]).

Remark 4.1. The parallelization of the modular algorithm is attained via multiple processes organized by SINGULAR library code. Consequently, a future aim is to enable parallelization in the kernel via multiple threads.

We choose the following examples to emphasize the superiority of modular solving and especially its parallelization:

Example 4.2. Cyclic_7.xml (cf. [G13]).

Example 4.3. Verschelde_noon6.xml (cf. [G13]).

Example 4.4. Pfister_1.xml (cf. [G13]).

Example 4.5. Pfister_2.xml (cf. [G13]).

Table 1 summarizes the results where modSolve(c) denotes the parallelized version of the algorithm applied on c cores. All timings are given in seconds.

Remark 4.6. Various experiments reveal that a sensitive choice of $\#\mathcal{P}$, the number of random primes in lines 1 and 13 in Algorithm 2, can decrease the running time enormously. To sum up, it is recommendable to relate c, the number of available cores, to $\#\mathcal{P}$. Particularly, in case of having more than ten cores to ones's disposal it is reasonable to set $c = \#\mathcal{P}$.

Example	solve	modSolve	modSolve(10)	modSolve(20)
4.2	> 18h	692	217	152
4.3	517	1223	522	371
4.4	526	800	288	165
4.5	2250	1276	323	160

TABLE 1. Total running times in seconds for computing all roots of the considered examples via solve, modSolve and its parallelized variant modSolve(c) for c = 10, 20.

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